Contents

	Preface to the first edition		*page* ix
	Preface to the second edition		xiii
	Acknowledgements		xv
	PART ONE TURBULENCE		1
1	**Introduction**		3
	1.1	Turbulence	3
	1.2	Low-dimensional models	5
	1.3	The contents of this book	8
	1.4	Notation and mathematical jargon	11
2	**Coherent structures**		17
	2.1	Introduction	17
	2.2	Flows with coherent structures	21
	2.3	Detection of coherent structures	32
	2.4	The mixing layer	35
	2.5	The turbulent boundary layer	50
	2.6	A preview of things to come	65
3	**Proper orthogonal decomposition**		68
	3.1	Introduction	69
	3.2	On domains and averaging	73
	3.3	Properties of the POD	74
	3.4	Further results	86
	3.5	Stochastic estimation	91
	3.6	Coherent structures and homogeneity	93
	3.7	Some applications	96
	3.8	Appendix: some foundations	100
4	**Galerkin projection**		106
	4.1	Introduction	106
	4.2	Some simple PDEs revisited	110

	4.3	The Navier–Stokes equations	116
	4.4	Towards low-dimensional models	121
5	**Balanced proper orthogonal decomposition**		130
	5.1	Balanced truncation	131
	5.2	Balanced POD	133
	5.3	Output projection	136
	5.4	Connections with standard POD	137
	5.5	Extensions of balanced POD	139
	5.6	Some examples	143
	PART TWO DYNAMICAL SYSTEMS		153
6	**Qualitative theory**		155
	6.1	Linearization and invariant manifolds	156
	6.2	Periodic orbits and Poincaré maps	162
	6.3	Structural stability and genericity	165
	6.4	Bifurcations local and global	168
	6.5	Attractors simple and strange	179
7	**Symmetry**		190
	7.1	Equivariant vector fields	190
	7.2	Local bifurcation with symmetry	194
	7.3	Global behavior with symmetry	195
	7.4	An $O(2)$-equivariant ODE	202
	7.5	Traveling modes	211
8	**One-dimensional "turbulence"**		214
	8.1	Projection onto Fourier modes	215
	8.2	Local bifurcations from $u = 0$	217
	8.3	The second bifurcation point	220
	8.4	Spatio-temporal chaos	226
9	**Randomly perturbed systems**		236
	9.1	An Ornstein–Uhlenbeck process	237
	9.2	Noisy heteroclinic cycles	240
	9.3	Power spectra of homoclinic attractors	247
	9.4	Symmetry breaking	249
	PART THREE THE BOUNDARY LAYER		253
10	**Low-dimensional models**		255
	10.1	Equations for coherent structures	256
	10.2	The eigenfunction expansion	259
	10.3	Symmetries	260
	10.4	Galerkin projection	262
	10.5	Geometrical structure of the model	269

10.6 Choosing subspaces and domains 272
10.7 The energy budget 275
10.8 Nonlinear feedback 281
10.9 Interaction with unresolved modes 285

11 Behavior of the models 289
11.1 Backbones for the models 290
11.2 Heteroclinic cycles 293
11.3 Bursts and sweeps 297
11.4 The pressure term 299
11.5 More modes and instabilities 303
11.6 A tentative summary 307
11.7 Appendix: coefficients 312

PART FOUR OTHER APPLICATIONS AND RELATED WORK 315

12 Some other fluid problems 317
12.1 The circular jet 317
12.2 The transitional boundary layer 321
12.3 A forced transitional mixing layer 326
12.4 Flows in complex geometries 328
12.5 "Full channel" wall layer models 331
12.6 Flows in internal combustion engines 335
12.7 A miscellany of results: 1995–2011 341
12.8 Discussion 342

13 Review: prospects for rigor 345
13.1 The quality of models 345
13.2 A short-time tracking estimate 349
13.3 Stability, simulations, and statistics 352
13.4 Spatial localization 356
13.5 The utility of models 360

References 364
Index 382