

Contents

| | |
|--|-----------|
| 1 ■ Survey of the Elementary Principles | 1 |
| 1.1 Mechanics of a Particle | 1 |
| 1.2 Mechanics of a System of Particles | 5 |
| 1.3 Constraints | 12 |
| 1.4 D'Alembert's Principle and Lagrange's Equations | 16 |
| 1.5 Velocity-Dependent Potentials and the Dissipation Function | 22 |
| 1.6 Simple Applications of the Lagrangian Formulation | 24 |
| 2 ■ Variational Principles and Lagrange's Equations | 34 |
| 2.1 Hamilton's Principle | 34 |
| 2.2 Some Techniques of the Calculus of Variations | 36 |
| 2.3 Derivation of Lagrange's Equations from Hamilton's Principle | 44 |
| 2.4 Extension of Hamilton's Principle to Nonholonomic Systems | 45 |
| 2.5 Advantages of a Variational Principle Formulation | 51 |
| 2.6 Conservation Theorems and Symmetry Properties | 54 |
| 2.7 Energy Function and the Conservation of Energy | 60 |
| 3 ■ The Central Force Problem | 70 |
| 3.1 Reduction to the Equivalent One-Body Problem | 70 |
| 3.2 The Equations of Motion and First Integrals | 72 |
| 3.3 The Equivalent One-Dimensional Problem, and Classification of Orbits | 76 |
| 3.4 The Virial Theorem | 83 |
| 3.5 The Differential Equation for the Orbit, and Integrable Power-Law Potentials | 86 |
| 3.6 Conditions for Closed Orbits (Bertrand's Theorem) | 89 |
| 3.7 The Kepler Problem: Inverse-Square Law of Force | 92 |
| 3.8 The Motion in Time in the Kepler Problem | 96 |
| 3.9 The Laplace–Runge–Lenz Vector | 103 |
| 3.10 Scattering in a Central Force Field | 106 |
| 3.11 Transformation of the Scattering Problem to Laboratory Coordinates | 115 |
| 3.12 The Three-Body Problem | 121 |

| | |
|--|------------|
| 4 ■ The Kinematics of Rigid Body Motion | 134 |
| 4.1 The Independent Coordinates of a Rigid Body | 134 |
| 4.2 Orthogonal Transformations | 139 |
| 4.3 Formal Properties of the Transformation Matrix | 144 |
| 4.4 The Euler Angles | 150 |
| 4.5 The Cayley–Klein Parameters and Related Quantities | 154 |
| 4.6 Euler’s Theorem on the Motion of a Rigid Body | 155 |
| 4.7 Finite Rotations | 161 |
| 4.8 Infinitesimal Rotations | 163 |
| 4.9 Rate of Change of a Vector | 171 |
| 4.10 The Coriolis Effect | 174 |
| 5 ■ The Rigid Body Equations of Motion | 184 |
| 5.1 Angular Momentum and Kinetic Energy of Motion about a Point | 184 |
| 5.2 Tensors | 188 |
| 5.3 The Inertia Tensor and the Moment of Inertia | 191 |
| 5.4 The Eigenvalues of the Inertia Tensor and the Principal Axis Transformation | 195 |
| 5.5 Solving Rigid Body Problems and the Euler Equations of Motion | 198 |
| 5.6 Torque-free Motion of a Rigid Body | 200 |
| 5.7 The Heavy Symmetrical Top with One Point Fixed | 208 |
| 5.8 Precession of the Equinoxes and of Satellite Orbits | 223 |
| 5.9 Precession of Systems of Charges in a Magnetic Field | 230 |
| 6 ■ Oscillations | 238 |
| 6.1 Formulation of the Problem | 238 |
| 6.2 The Eigenvalue Equation and the Principal Axis Transformation | 241 |
| 6.3 Frequencies of Free Vibration, and Normal Coordinates | 250 |
| 6.4 Free Vibrations of a Linear Triatomic Molecule | 253 |
| 6.5 Forced Vibrations and the Effect of Dissipative Forces | 259 |
| 6.6 Beyond Small Oscillations: The Damped Driven Pendulum and the Josephson Junction | 265 |
| 7 ■ The Classical Mechanics of the Special Theory of Relativity | 276 |
| 7.1 Basic Postulates of the Special Theory | 277 |
| 7.2 Lorentz Transformations | 280 |
| 7.3 Velocity Addition and Thomas Precession | 282 |
| 7.4 Vectors and the Metric Tensor | 286 |

| | | |
|-------------|--|------------|
| 7.5 | 1-Forms and Tensors | 289 |
| 7.6 | Forces in the Special Theory; Electromagnetism | 297 |
| 7.7 | Relativistic Kinematics of Collisions and Many-Particle Systems | 300 |
| 7.8 | Relativistic Angular Momentum | 309 |
| 7.9 | The Lagrangian Formulation of Relativistic Mechanics | 312 |
| 7.10 | Covariant Lagrangian Formulations | 318 |
| 7.11 | Introduction to the General Theory of Relativity | 324 |
| 8 ■ | The Hamilton Equations of Motion | 334 |
| 8.1 | Legendre Transformations and the Hamilton Equations of Motion | 334 |
| 8.2 | Cyclic Coordinates and Conservation Theorems | 343 |
| 8.3 | Routh's Procedure | 347 |
| 8.4 | The Hamiltonian Formulation of Relativistic Mechanics | 349 |
| 8.5 | Derivation of Hamilton's Equations from a Variational Principle | 353 |
| 8.6 | The Principle of Least Action | 356 |
| 9 ■ | Canonical Transformations | 368 |
| 9.1 | The Equations of Canonical Transformation | 368 |
| 9.2 | Examples of Canonical Transformations | 375 |
| 9.3 | The Harmonic Oscillator | 377 |
| 9.4 | The Symplectic Approach to Canonical Transformations | 381 |
| 9.5 | Poisson Brackets and Other Canonical Invariants | 388 |
| 9.6 | Equations of Motion, Infinitesimal Canonical Transformations, and Conservation Theorems in the Poisson Bracket Formulation | 396 |
| 9.7 | The Angular Momentum Poisson Bracket Relations | 408 |
| 9.8 | Symmetry Groups of Mechanical Systems | 412 |
| 9.9 | Liouville's Theorem | 419 |
| 10 ■ | Hamilton–Jacobi Theory and Action-Angle Variables | 430 |
| 10.1 | The Hamilton–Jacobi Equation for Hamilton's Principal Function | 430 |
| 10.2 | The Harmonic Oscillator Problem as an Example of the Hamilton–Jacobi Method | 434 |
| 10.3 | The Hamilton–Jacobi Equation for Hamilton's Characteristic Function | 440 |
| 10.4 | Separation of Variables in the Hamilton–Jacobi Equation | 444 |
| 10.5 | Ignorable Coordinates and the Kepler Problem | 445 |
| 10.6 | Action-angle Variables in Systems of One Degree of Freedom | 452 |

| | | |
|---------------------|--|------------|
| 10.7 | Action-Angle Variables for Completely Separable Systems | 457 |
| 10.8 | The Kepler Problem in Action-angle Variables | 466 |
| 11 ■ | Classical Chaos | 483 |
| 11.1 | Periodic Motion | 484 |
| 11.2 | Perturbations and the Kolmogorov–Arnold–Moser Theorem | 487 |
| 11.3 | Attractors | 489 |
| 11.4 | Chaotic Trajectories and Liapunov Exponents | 491 |
| 11.5 | Poincaré Maps | 494 |
| 11.6 | Hénon–Heiles Hamiltonian | 496 |
| 11.7 | Bifurcations, Driven-damped Harmonic Oscillator, and Parametric Resonance | 505 |
| 11.8 | The Logistic Equation | 509 |
| 11.9 | Fractals and Dimensionality | 516 |
| 12 ■ | Canonical Perturbation Theory | 526 |
| 12.1 | Introduction | 526 |
| 12.2 | Time-dependent Perturbation Theory | 527 |
| 12.3 | Illustrations of Time-dependent Perturbation Theory | 533 |
| 12.4 | Time-independent Perturbation Theory | 541 |
| 12.5 | Adiabatic Invariants | 549 |
| 13 ■ | Introduction to the Lagrangian and Hamiltonian Formulations for Continuous Systems and Fields | 558 |
| 13.1 | The Transition from a Discrete to a Continuous System | 558 |
| 13.2 | The Lagrangian Formulation for Continuous Systems | 561 |
| 13.3 | The Stress-energy Tensor and Conservation Theorems | 566 |
| 13.4 | Hamiltonian Formulation | 572 |
| 13.5 | Relativistic Field Theory | 577 |
| 13.6 | Examples of Relativistic Field Theories | 583 |
| 13.7 | Noether’s Theorem | 589 |
| Appendix A ■ | Euler Angles in Alternate Conventions and Cayley–Klein Parameters | 601 |
| Appendix B ■ | Groups and Algebras | 605 |
| | Selected Bibliography | 617 |
| | Author Index | 623 |
| | Subject Index | 625 |

