

CONTENTS

Preface, vii

Introduction, xiii

Chapter 1. Mathematical preliminaries, 1

- 1.1 Tensor formulas in three-dimensional Euclidean spaces, 2
- 1.2 Tensor fomulas for surfaces, 6
- 1.3 Basic concepts and definitions in the theory of abstract spaces and operators, 13
 - 1.3.1 Normed, inner-product, Banach and Hilbert spaces, 14
 - 1.3.2 Operators and functionals, 16
- 1.4 Fundamentals of the classical calculus of variations, 18
 - 1.4.1 Variations and variational notation, 18
 - 1.4.2 Euler differential equations – Boundary conditions, 20
 - 1.4.3 Illustrative example, 21
 - 1.4.4 Variational problems with constraints, 22
 - 1.4.5 The Legendre transformation, 24
- 1.5 Differentials and derivatives of operators – Variations, 25
 - 1.5.1 Gâteaux and Fréchet differentials and derivatives, 25
 - 1.5.2 Gradient of a functional – Potential operators, 27
 - 1.5.3 Generalizations, partial derivatives, Taylor formulas, the Legendre transformation, 30
 - 1.5.4 The formal adjoint of operators, 31
 - 1.5.5 Illustrative examples, 34
- 1.6 Variational boundary value problems, 36
- 1.7 Variational methods of approximation, 39

Part I – Three-dimensional theory, 41

Chapter 2. Kinematics and stress in three-dimensional solid continua, 42

- 2.1 Description of motion, coordinates, reference and deformed states, 42
- 2.2 Kinematics of deformation, 45
 - 2.2.1 The strain tensor, 45
 - 2.2.2 Relationships between surface elements, 51
 - 2.2.3 Velocities – Accelerations – Strain rates, 54
- 2.3 Kinematics of incremental deformation, 58
- 2.4 Definitions of stress – Stress rates, 66
- 2.5 Incremental stresses, 73
- 2.6 External loadings – Boundary conditions, 79
- 2.7 Illustrative example of physical components of displacements and stress, 81

Chapter 3. General principles – The First and the Second Laws of Thermodynamics, 83

- 3.1 Kinematics of rigid body motions – Invariance requirements, 83
- 3.2 The First Law of Thermodynamics, 84
 - 3.2.1 Global form of the First Law – Invariance conditions, 85
 - 3.2.2 Local forms and consequences of the First Law, 90
 - 3.2.3 Incremental form of the First Law of Thermodynamics, 92
- 3.3 The Second Law of Thermodynamics, 96
 - 3.3.1 Formulation of the Second Law, 96
 - 3.3.2 Dissipative stresses, internal parameters, 97
 - 3.3.3 Thermodynamic and dissipation functions, 99
 - 3.3.4 Structural damping, 102
- 3.4 The Principles of Virtual Displacements and Virtual Forces, 103
 - 3.4.1 The Principle of Virtual Displacements, 103
 - 3.4.2 The Principle of Virtual Forces, 108
- 3.5 Equations of equilibrium in physical components for cylindrical and spherical coordinates, 110

Chapter 4. Constitutive material laws, 112

- 4.1 Elastic, hypoelastic and hyperelastic materials, 112
 - 4.1.1 Strain and complementary energy functions for Hookean solids, 117
 - 4.1.2 Thermodynamic functions for isotropic Hookean solids – Thermoelastic coupling, 119
 - 4.1.3 Hyperelastic incremental constitutive relations, 121
- 4.2 Elastic-plastic materials, 123
- 4.3 Visco-elastic materials, 126

Part II – Shell theory, 129

Chapter 5. Deformation and stress in shells, 130

- 5.1 Shell middle surface: coordinates, base vectors, 131
- 5.2 Description of deformation and motion in shells, 133
 - 5.2.1 The three-dimensional approach, 133
 - 5.2.2 Deformation of the shell middle surface, 136
 - 5.2.3 The Cosserat model for the shell middle surface, 141
 - 5.2.4 Interpretation of different deformation measures – Special cases, 144
 - 5.2.5 Velocities, strain rates and acceleration vectors, 147
- 5.3 Kinematics of incremental deformation in shells, 152
- 5.4 Stress resultants and stress couples for shells – Three-dimensional approach, 160
 - 5.4.1 Definitions of stress resultants and stress couples, 160
 - 5.4.2 Virtual work, energy of deformation – Discussion, 166
 - 5.4.3 Boundary stress vectors and boundary couples, 170
 - 5.4.4 Incremental stress resultants and stress couples, 171
 - 5.4.5 Incremental boundary stress vectors and couples, 175
- 5.5 Load vectors and incremental load vectors, 178

Chapter 6. The First Law of Thermodynamics applied to shells – General principles, 179

- 6.1 Formulation of the First Law – Invariance requirements, 179
- 6.2 Reduced and local forms of the First Law, 182
- 6.3 The First Law in the reference state, 187
- 6.4 Some consequences of the First Law – Discussion – Boundary condition, 192
- 6.5 Incremental forms of the First Law of Thermodynamics, 199
- 6.6 Incremental theory and stability, 204
- 6.7 The Principles of Virtual Displacements and Virtual Forces for shells, 204

Chapter 7. Constitutive relations and material laws for shells, 211

- 7.1 Material laws for thin elastic shells, 211
- 7.2 Hyperelastic incremental material relations, 215
- 7.3 A note on the constitutive relations for inelastic shells, 218

Part III. Variational principles, finite element models and applications, elastic stability, 219

Chapter 8. Variational principles of elasticity and shell theory – Classical approach, 220

- 8.1 Variational principles of three-dimensional elasticity, 220
 - 8.1.1 The Principle of Stationary Potential Energy, 220
 - 8.1.2 The Principle of Stationary Complementary Energy, 222
 - 8.1.3 Generalized variational principles, 223
- 8.2 Variational principles of elastic shell theory, 228
 - 8.2.1 The Principles of Stationary Potential Energy and Stationary Complementary Energy, 229
 - 8.2.2 Generalized variational principles, 232
- 8.3 Special cases – the Principles of Reciprocity, Clapeyron, Castigliano and Menabrea, 234
 - 8.3.1 The Principles of Clapeyron, Castigliano and Menabrea, 234
 - 8.3.2 The Reciprocity Principle, 235
- 8.4 General remarks – The role of Legendre transformation, 236
- 8.5 Illustrative Examples, 237
 - 8.5.1 The kinematic relations of linear shell theory, by means of the principle of stationary complementary energy, 237
 - 8.5.2 The equations of shallow shell theory with large displacements, 239
 - 8.5.3 The classical solutions of plate theory, 243
- 8.6 Variational principles – Weak solutions, 243

Chapter 9. Variational and incremental principles – General abstract approach, 245

- 9.1 Basic equations and operators, 245
- 9.2 Inner products-Formal adjoints – Special notations and admissible variations, 250
- 9.3 The Principles of Virtual Displacements and Virtual Forces, 256
- 9.4 General conditions for potentialness of the operators of dynamics and kinematics, 262
- 9.5 Strain and complementary energy – Loading Potentials, 262

- 9.6 General variational principles derived from the Principles of Virtual Displacements and Virtual Forces, 264
- 9.7 The variational principles of non-linear elasticity and elastic shell theory, 268
- 9.8 Incremental variational principles, 270
- 9.9 Incremental principles of non-linear elasticity and shallow shell theory, 276

Chapter 10. Finite element models – Selected applications, 279

- 10.1 Matrix representation of important results, 279
 - 10.1.1 Three-dimensional theory formulas, 279
 - 10.1.2 Shell theory formulas, 287
- 10.2 Matrix formulas for physical components, 291
- 10.3 Finite element models – Stiffness, flexibility and tangent matrices, 292
 - 10.3.1 Local and global functions – Element representation, 295
 - 10.3.2 Kinematic finite element models, 298
 - 10.3.3 Mixed, equilibrium and generalized finite element models, 302
 - 10.3.4 The finite element method and the Ritz Galerkin approximations, 306
- 10.4 The numerical solution of finite element equations in statics and dynamics, 306
- 10.5 Illustrative examples, 309
 - 10.5.1 Basic matrices in linear shell theory, 309
 - 10.5.2 Basic matrices in non-linear shallow shell theory, 313
 - 10.5.3 Stress mixed beam element, 315
- 10.6 The problem of initial stresses and temperature effects, 316
- 10.7 Variational problems with discontinuous fields, 318
- 10.8 Concluding remark, 321

Chapter 11. Elastic stability, 322

- 11.1 Incremental expansions for the potential energy, 323
- 11.2 Neutral equilibrium – Critical state, 327
- 11.3 Illustrative examples, 330
 - 11.3.1 The effect of initial stresses on the buckling loads of Euler columns, 330
 - 11.3.2 The linear buckling equations of cylindrical shells subject to compression and torsion, 333
- 11.4 General theory of elastic stability – Postbuckling behaviour, 336
- 11.5 Stability of an equilibrium state, 337
- 11.6 Critical behaviour, 339
- 11.7 Limit points and branching points, 341
- 11.8 Imperfection sensitivity, coincident branching points and multiparameter loadings, 347
- 11.9 Critical and limit points – Illustrative examples, 348
 - 11.9.1 Limit and critical points in one-degree of freedom systems, 349
 - 11.9.2 Incremental potential energy expressions for shallow spherical caps, 352
- 11.10 Stability and tangent stiffness matrix – Concluding remarks, 357

Selected references, 358

Index, 365