CONTENTS

Chapter I KINEMATIC SPACE - THE ARENA OF NEWTONIAN MECHANICS

1. Preliminary Remarks and Notation 1
2. Inertial Frame of Reference and Newtonian Motions . 2
3. Configuration Space, Event Space 3
4. Kinematic Space. 5
5. The Structure of Kinematic Space 8
6. Behavior Under Mappings 16
7. Horizontal Vector Fields and Variations. 27
8. Variations and Constraints 31
9. Variational Processes. 35
10. Mapping Properties of Variations 38
11. Extended Variations 42

Chapter II NEWTONIAN MOTIONS IN KINEMATIC SPACE

12. The Mass Tensor and Newtonian Motions 44
13. The First Reformulation 46
14. The Second Reformulation - Lagrange's Equations . . 48
15. Transformation Properties of Lagrange's Equations . 50

Chapter III ANALYSIS OF FORCES

16. Conservative Forces 53
17. Variational Forces. 59
18. The Canonical Representations of Darboux 61
19. Motions under Nonconservative Forces. 65
20. The Dissipative and Nondissipative Parts of W . . 68
21. The Unique Potential Representation 72

Chapter IV ANALYSIS OF CONSTRAINTS

22. The Classic Theory and its Extension. 80

23. Newtonian Motions of Conservative Systems with Extended Constraints 83

24. Forces that Maintain Given Constraints and Related Topics. 85

25. Integrable Constraints - Application of the Frobenius Theorem 88

26. Nonintegrable Constraints - Application of Cartan Systems 97

27. Catastatic Constraints in the General Case. 99

Chapter V FUNDAMENTAL DIFFERENTIAL FORMS I. VARIATIONAL SYSTEMS

28. General Variational Systems. 102

29. The Fundamental Differential Form. 103

30. Invariance and Quadratures 107

31. The Search for Quadratures Continued. 111

32. Group Properties of Kinematic Space 116

33. Proof of the Fundamental Theorem on Maximal Mobility Groups. 119

34. Quadratures, Group Orbits and Related Topics . . . 126

Chapter VI FUNDAMENTAL DIFFERENTIAL FORMS 2. NONCONSERVATIVE NONHOLONOMIC SYSTEMS

35. Nonconservative, Nonholonomic Dynamical Systems . . 133

36. The Fundamental Differential Form. 136

37. The Fundamental 2-Form 139

38. Quadratures 142

39. A Uniform Reformulation 145

Chapter VII INTEGRAL FORMS OF CONSERVATION AND BALANCE

40. Families of Newtonian Motions for Variational Systems 148

41. Absolute and Relative Integral Invariants of Variational Systems 155

42. Derivation of Lagrange's Equations from a Relative Integral Invariant. 162

43. Families of Newtonian Motions in the General Case . 166
44. Balance Forms and Integral Balance Laws. 168
45. Derivation of the Equations of Motion from a Balance Form. 174

Chapter VIII A TRANSFORMATION-THEORETIC APPROACH

46. Lagrange Transformations of Variational Systems . . 176
47. Properties of Lagrange Transformations 179
48. Transformation-Theoretic Solutions - The Lagrangian Mechanics Analog of Hamilton-Jacobi Theory. . . . 184
49. A Useful Alternative - Solution by Means of a Particular Integral 189
50. E-Transformations of Nonconservative, Nonholonomic Systems 192
51. Properties of E-Transformations 194

Chapter IX FIELD MECHANICS FOR SYSTEMS WITH LAWS OF BALANCE

52. Kinematic Space and Related Topics 199
53. Behavior under Mappings 205
54. Laws of Balance and their Fundamental Differential Forms 209
55. Noetherian Vector Fields and their Associated Currents 218
56. Variational Systems 227
57. E-Transformations 236
58. F-Transformations 249

APPENDIX

A1. Preliminary Considerations, Points and Coordinate Covers. 257
A2. Vector Fields 258
A3. Exterior Forms and Exterior Products. 261
A4. The Exterior Derivative 264
A5. Algebraic Results 267
A6. Inner Multiplication 270

A7. Behavior under Maps 271
A8. Lie Differentiation 274
A9. The Theorems of Frobenius and Darboux 279
A10. The Poincaré Lemma and the Homotopy Operator H . . 283
A11. Solutions of Exterior Differential Equations . . . 286
A12. Integration of Exterior Forms and Stokes' Theorem . 291

REFERENCES 294
INDEX. 296
LIST OF FREQUENTLY USED SYMBOLS 301