	S.₹	

Contents

Prelace	A 11
Chapter I. Hamiltonian Differential Equations and the N-Body Problem	1
A. Background and Basic Definitions	1
Notation, Hamiltonian systems, Poisson bracket	
B. Examples of Hamiltonian Systems	5
The harmonic oscillator, forced nonlinear oscillator, the elliptic	
sine function, general Newtonian systems, a pair of harmonic	
oscillators, linear flow on the torus, the Kirchhoff problem	
C. The N-Body Problem	17
The equations, the classical integrals, the Kepler problem, the	
restricted 3-body problem	
D. Simple Solutions	21
Central configurations, the Lagrangian equilateral triangle	
solutions, the Euler–Moulton collinear solutions, equilibria for	
the restricted three-body problem	
E. Further Reading	28
Problems	29
Chantan II - I in ann II amiltonian Cretome	33
Chapter II. Linear Hamiltonian Systems	33
A. Preliminaries	33
Hamiltonian & symplectic matrices, reduction with a Lagrangian	
Set December 1 de la companya de la comp	40
B. Symplectic Linear Spaces	40
Symplectic basis, Lagrangian splitting	44
C. The Spectra of Hamiltonian and Symplectic Operators	44
Characteristic equations, J-orthogonal, simple canonical forms	

٦		t	9	,
	٦		ľ	
	ı		8	Ľ

_		
('~	+00	240
Con		

D. Nonelementary Divisors	50
General canonical forms E. Dorio dio Systems and Elegents I.	
E. Periodic Systems and Floquet-Lyapunov Theory	53
Multipliers, monodromy matrix, Liapunov transformation F. Parametric Stability	5.6
Stability, parametric stability & instability	56
G. The Critical Points in the Restricted Problem	59
Linear equations at Euler & Lagrange points, Routh's critical	33
mass ratio, canonical forms	
H. Further Reading	67
Appendix. Logarithm of a Symplectic Matrix	67
Problems	69
	0,7
Chapter III. Exterior Algebra and Differential Forms	72
A. Exterior Algebra	72
Multilinear, covector, k-form, determinant	
B. The Symplectic Form	76
Symplectic basis & form, determinant of a symplectic matrix	
C. Tangent Vectors and Cotangent Vectors	77
Contra- & co-variant vectors, Einstein convention	
D. Vector Fields and Differential Forms	79
Contra- & co-variant vector fields, differential forms, exterior	
derivative, Poincaré's lemma	
E. Changing Coordinates and Darboux's Theorem	83
Symplectic structure, symplectic coordinates, Darboux's	
theorem	
F. Integration and Stokes' Theorem	85
Problems .	85
Chapter IV. Symplectic Transformations and Coordinates	87
A. Symplectic Transformations	87
Definition, remainder function, variational equations	
B. Applications	91
Rotating coordinates, Jacobi coordinates. (special case $N=2$)	
C. Differential Forms and Generating Functions	95
Symplectic form, action-angle variables, d'Alembert character,	
generating functions, point transformations, Kepler's problem in	
polar coordinates, the 3-body problem in Jacobi and Jacobi-Polar	•
coordinates	
D. Symplectic Transformations with Multipliers and Scaling.	102
Gravitational constant, Equations at an equilibrium point, the	
restricted three body problem	
E. Delaunay and Poincaré Elements	104
F. Further Reading	107
Problems	107

79

A. Introduction to Dynamical Systems Orbit, trajectory, equilibrium point, period orbit, Hamiltonian dynamical Systems, reparameterization B. Discrete Dynamical Systems Diffeomorphisms and symplectomorphisms, Henon map, time τ-map, period map, isotopy, billiards table, crystal model C. The Flow Box Theorem and Local Integrals Ordinary point, local integrals, Hamiltonian flow box, integrals in involution, ignorable coordinates D. Noether's Theorem and Reduction Discrete and continuous symmetry, reversible system, Noether's Theorem E. Periodic Solutions, Fixed Points, and Cross Sections Elementary equilibrium points & periodic orbits, multipliers, cross section, Poincare map, systems with integrals, the cylinder theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function B. The Perturbation Algorithm	Chap	ter V. Introduction to the Geometric Theory of Hamiltonian	
Orbit, trajectory, equilibrium point, period orbit, Hamiltonian dynamical system, reparameterization B. Discrete Dynamical Systems Diffeomorphisms and symplectomorphisms, Henon map, time τ-map, period map, isotopy, billiards table, crystal model C. The Flow Box Theorem and Local Integrals Ordinary point, local integrals, Hamiltonian flow box, integrals in involution, ignorable coordinates D. Noether's Theorem and Reduction Discrete and continuous symmetry, reversible system, Noether's Theorem E. Periodic Solutions, Fixed Points, and Cross Sections Elementary equilibrium points & periodic orbits, multipliers, cross section, Poincare map, systems with integrals, the cylinder theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems Chapter VI. Continuation of Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			109
Orbit, trajectory, equilibrium point, period orbit, Hamiltonian dynamical system, reparameterization B. Discrete Dynamical Systems Diffeomorphisms and symplectomorphisms, Henon map, time τ-map, period map, isotopy, billiards table, crystal model C. The Flow Box Theorem and Local Integrals Ordinary point, local integrals, Hamiltonian flow box, integrals in involution, ignorable coordinates D. Noether's Theorem and Reduction Discrete and continuous symmetry, reversible system, Noether's Theorem E. Periodic Solutions, Fixed Points, and Cross Sections Elementary equilibrium points & periodic orbits, multipliers, cross section, Poincare map, systems with integrals, the cylinder theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems Chapter VI. Continuation of Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function	A.	Introduction to Dynamical Systems	109
B. Discrete Dynamical Systems Diffeomorphisms and symplectomorphisms, Henon map, time τ-map, period map, isotopy, billiards table, crystal model C. The Flow Box Theorem and Local Integrals Ordinary point, local integrals, Hamiltonian flow box, integrals in involution, ignorable coordinates D. Noether's Theorem and Reduction Discrete and continuous symmetry, reversible system, Noether's Theorem E. Periodic Solutions, Fixed Points, and Cross Sections Elementary equilibrium points & periodic orbits, multipliers, cross section, Poincare map, systems with integrals, the cylinder theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems Chapter VI. Continuation of Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			
B. Discrete Dynamical Systems Diffeomorphisms and symplectomorphisms, Henon map, time t-map, period map, isotopy, billiards table, crystal model C. The Flow Box Theorem and Local Integrals Ordinary point, local integrals, Hamiltonian flow box, integrals in involution, ignorable coordinates D. Noether's Theorem and Reduction Discrete and continuous symmetry, reversible system, Noether's Theorem E. Periodic Solutions, Fixed Points, and Cross Sections Elementary equilibrium points & periodic orbits, multipliers, cross section, Poincare map, systems with integrals, the cylinder theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems 144 Problems 152 Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 166 Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			
Diffeomorphisms and symplectomorphisms, Henon map, time τ-map, period map, isotopy, billiards table, crystal model C. The Flow Box Theorem and Local Integrals Ordinary point, local integrals, Hamiltonian flow box, integrals in involution, ignorable coordinates D. Noether's Theorem and Reduction Discrete and continuous symmetry, reversible system, Noether's Theorem E. Periodic Solutions, Fixed Points, and Cross Sections Elementary equilibrium points & periodic orbits, multipliers, cross section, Poincare map, systems with integrals, the cylinder theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems 152 Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems Chapter VII. Perturbation Theory and Normal Forms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function	В.		113
T-map, period map, isotopy, billiards table, crystal model C. The Flow Box Theorem and Local Integrals Ordinary point, local integrals, Hamiltonian flow box, integrals in involution, ignorable coordinates D. Noether's Theorem and Reduction Discrete and continuous symmetry, reversible system, Noether's Theorem E. Periodic Solutions, Fixed Points, and Cross Sections Elementary equilibrium points & periodic orbits, multipliers, cross section, Poincare map, systems with integrals, the cylinder theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems Chapter VI. Continuation of Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems Chapter VII. Perturbation Theory and Normal Forms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			, - ,
C. The Flow Box Theorem and Local Integrals Ordinary point, local integrals, Hamiltonian flow box, integrals in involution, ignorable coordinates D. Noether's Theorem and Reduction Discrete and continuous symmetry, reversible system, Noether's Theorem E. Periodic Solutions, Fixed Points, and Cross Sections Elementary equilibrium points & periodic orbits, multipliers, cross section, Poincare map, systems with integrals, the cylinder theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems Chapter VI. Perturbation Theory and Normal Forms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			
Ordinary point, local integrals, Hamiltonian flow box, integrals in involution, ignorable coordinates D. Noether's Theorem and Reduction Discrete and continuous symmetry, reversible system, Noether's Theorem E. Periodic Solutions, Fixed Points, and Cross Sections Elementary equilibrium points & periodic orbits, multipliers, cross section, Poincare map, systems with integrals, the cylinder theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems Chapter VI. Continuation of Periodic Solutions Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems Chapter VII. Perturbation Theory and Normal Forms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function	C.		120
in involution, ignorable coordinates D. Noether's Theorem and Reduction Discrete and continuous symmetry, reversible system, Noether's Theorem E. Periodic Solutions, Fixed Points, and Cross Sections Elementary equilibrium points & periodic orbits, multipliers, cross section, Poincare map, systems with integrals, the cylinder theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems 152 Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 168 Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			
D. Noether's Theorem and Reduction Discrete and continuous symmetry, reversible system, Noether's Theorem E. Periodic Solutions, Fixed Points, and Cross Sections Elementary equilibrium points & periodic orbits, multipliers, cross section, Poincare map, systems with integrals, the cylinder theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems 152 Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 164 H. Further Reading Problems 165 A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			
Theorem E. Periodic Solutions, Fixed Points, and Cross Sections Elementary equilibrium points & periodic orbits, multipliers, cross section, Poincare map, systems with integrals, the cylinder theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems 152 Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 168 A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function	D.	THE AND THE THE STATE OF THE ST	125
Theorem E. Periodic Solutions, Fixed Points, and Cross Sections Elementary equilibrium points & periodic orbits, multipliers, cross section, Poincare map, systems with integrals, the cylinder theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems 152 Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 168 A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function		Discrete and continuous symmetry, reversible system, Noether's	
Elementary equilibrium points & periodic orbits, multipliers, cross section, Poincare map, systems with integrals, the cylinder theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems 152 Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 168 A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			
Elementary equilibrium points & periodic orbits, multipliers, cross section, Poincare map, systems with integrals, the cylinder theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems 152 Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 168 A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function	E.	Periodic Solutions, Fixed Points, and Cross Sections	129
cross section, Poincare map, systems with integrals, the cylinder theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems 149 Problems 152 Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 166 Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			
theorem F. The Stable Manifold Theorem Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma 149 Problems 152 Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 168 A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			
Hyperbolic point, local and global stable and unstable manifold, transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems 152 Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 168 A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			
transversal homoclinic point, the λ-lemma, the Poincare tangle G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma 149 Problems 152 Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 166 Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function	F.	The Stable Manifold Theorem	136
G. Hyperbolic Systems H. Further Reading Appendix. Proof of Shadowing Lemma Problems 149 Problems 152 Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 168 A. The Method of Lie Transforms A. The Method of Lie Transforms A. The Method of Lie Transforms Algorithm, the remainder function		Hyperbolic point, local and global stable and unstable manifold,	
H. Further Reading Appendix. Proof of Shadowing Lemma 149 Problems 152 Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 166 Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function		transversal homoclinic point, the λ -lemma, the Poincare tangle	
Appendix. Proof of Shadowing Lemma Problems 152 Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 166 Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function	G.	Hyperbolic Systems	141
Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 168 A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function	H.	Further Reading	148
Chapter VI. Continuation of Periodic Solutions A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function	Ap	pendix. Proof of Shadowing Lemma	149
A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 166 Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function	Pro	oblems	152
A. Continuation of Equilibrium Points and Periodic Solutions B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems 166 Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function	_ han	ter VI. Continuation of Periodic Solutions	154
B. Lyapunov's Center Theorem Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function	200		
Applications to the Euler and Lagrange libration points C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function		* 	
C. Poincaré's Orbits D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			
D. Hill's Orbits E. Comets F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function	C.		158
E. Comets F. Continuation from the Restricted to the Full Problem 162 G. Some Elliptic Orbits H. Further Reading Problems 166 Problems 167 Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			
F. Continuation from the Restricted to the Full Problem G. Some Elliptic Orbits H. Further Reading Problems Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			161
G. Some Elliptic Orbits H. Further Reading Problems Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function	34444		162
H. Further Reading Problems Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			164
Problems Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			166
Chapter VII. Perturbation Theory and Normal Forms A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			
A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function	SEE SEEST		
A. The Method of Lie Transforms Near identity change of coordinates, the forward Lie transform algorithm, the remainder function	Chap	ter VII. Perturbation Theory and Normal Forms	168
Near identity change of coordinates, the forward Lie transform algorithm, the remainder function			
algorithm, the remainder function			
	В.		175
Example: Duffing's equation, the general algorithm, the general	and market if		eservitet vite i vite
perturbation theorem, Duffing's equation revisited, uniqueness of	ĝ?		
normal forms .			

C. Normal Form at an Equilibrium	182
The classic case, the general equilibria, example of normal forms	\$
in the non-simple case	
D. Normal Form at $\mathcal{L}_{\mathbf{A}}$	189
E. Normal Forms for Periodic Systems and Diffeomorphisms	190
The reduction, general periodic case, general hyperbolic and	(0 -1 0.7000000)
elliptic points, higher resonance in the planar case, normal forms	
when multipliers are ± 1	
F. Further Reading	199
Problems	199
Chapter VIII. Bifurcations of Periodic Orbits	201
A. Bifurcations of Periodic Solutions and Points.	201
Elementary fixed points, extremal fixed points, period doubling,	()
k-bifurcation points.	
B. Duffing Revisited.	212
Duffing at 1-1 resonance, k-bifurcation in Duffing's equation	
C. Schmidt's Bridges	216
D. Bifurcation of \mathscr{L}_{4}	218
E. Further Reading	224
Problems	224
Chapter IX. Stability and KAM Theory	227
A. Elementary Stability Results	227
B. The Invariant Curve Theorem	229
C. A Simple Example—Duffing's Equation Again	232
D. Applications to the Restricted Problem	233
E. Arnold's Theorem	235
F. Stability of \mathscr{L}_{4}	238
G. Further Reading	239
Problems	239
Chapter X. Twist Maps and Invariant Curves	241
A. Introduction	241
B. Notation and Definitions	242
C. Existence of Periodic Orbits	253
D. Monotone Orbits	255
E. Invariant Circles	266
F. Applications	274
G. Further Reading	274
Problems	277
References	279
Index	289

**		