Contents

Preface xv

Chapter 1. Introduction

Mathematical Models for Physical Systems 1

Chapter 2. Classical Mechanics

Mechanics of Many-Particle Systems 5
Lagrangian and Hamiltonian Formulation 7
Mechanical Systems with Constraints 11
Exercises 14

Chapter 3. Introduction to Differential Manifolds

Differential Calculus in Several Variables 16
The Concept of a Differential Manifold 23
Submanifolds 26
Tangent Vectors 28
Smooth Maps of Manifolds 33
Differentials of Functions 35
Exercises 36

Chapter 4. Differential Equations on Manifolds

Vector Fields and Integral Curves 39
Local Existence and Uniqueness Theory 40
The Global Flow of a Vector Field 53
Complete Vector Fields 55
Exercises 57

Chapter 5. The Tangent and Cotangent Bundles

The Topology and Manifold Structure of the Tangent Bundle 61
The Cotangent Space and the Cotangent Bundle 66
The Canonical 1-Form on T*X 68
Exercises 70

Chapter 6. Covariant 2-Tensors and Metric Structures

Covariant Tensors of Degree 2 72
The Index of a Metric 74
Riemannian and Lorentzian Metrics 74
Behavior Under Mappings 77
Induced Metrics on Submanifolds 79
Raising and Lowering Indices 83
The Gradient of a Function 84
Partitions of Unity 84
Existence of Metrics on a Differential Manifold 87
Topology and Critical Points of a Function 90
Exercises 92

Chapter 7. Lagrangian and Hamiltonian Mechanics for Holonomic Systems

Introduction 94
The Total Force Mapping 95
Forces of Constraint 96
Lagrange's Equations 99
Conservative Forces 99
The Legendre Transformation 103
Conservation of Energy 105
Hamilton's Equations 106
2-Forms 110
Exterior Derivative 112
Canonical 2-Form on T^*X 114
The Mappings # and ♭ 114
Hamiltonian and Lagrangian Vector Fields 115
Time-Dependent Systems 121
Exercises 124

Chapter 8. Tensors

Tensors on a Vector Space 127
Tensor Fields on Manifolds 129

The Lie Derivative 132
The Bracket of Vector Fields 135
Vector Fields as Differential Operators 137
Exercises 138

Chapter 9. Differential Forms

Exterior Forms on a Vector Space 141
Orientation of Vector Spaces 146
Volume Element of a Metric 149
Differential Forms on a Manifold 150
Orientation of Manifolds 151
Orientation of Hypersurfaces 154
Interior Product 156
Exterior Derivative 156
Poincaré Lemma 161
De Rham Cohomology Groups 161
Manifolds with Boundary 162
Induced Orientation 163
Hodge *-Duality 165
Divergence and Laplacian Operators 168
Calculations in Three-Dimensional Euclidean Space 168
Calculations in Minkowski Spacetime 170
Geometrical Aspects of Differential Forms 171
Smooth Vector Bundles 172
Vector Subbundles 172
Kernel of a Differential Form 173
Integrable Subbundles and the Frobenius Theorem 176
Integral Manifolds 184
Maximal Integral Manifolds 185
Inaccessibility Theorem 187
Nonintegrable Subbundles 188
Vector-Valued Differential Forms 189
Exercises 191

Chapter 10. Integration of Differential Forms

The Integral of a Differential Form 196
Stokes's Theorem 199
Transformation Properties of Integrals 201
ω-Divergence of a Vector Field 203
Other Versions of Stokes's Theorem 204
Integration of Functions 207
The Classical Integral Theorems 208
Exercises 210

Chapter 11. The Special Theory of Relativity

Basic Concepts and Relativity Groups 213
Relativistic Law of Velocity Addition 220
Relativity of Simultaneity 222
Relativistic Length Contraction 222
Relativistic Time Dilation 223
The Invariant Spacetime Interval 223
The Proper Lorentz Group and the Poincaré Group 224
The Spacetime Manifold of Special Relativity 225
Relativistic Time Units 227
Accelerated Motion—A Space Odyssey 229
Energy and Momentum 233
Relativistic Correction to Newtonian Mechanics 234
Conservation of Energy and Momentum 235
Mass and Energy 236
Changes in Rest Mass 236
Summary 237
Exercises 237

Chapter 12. Electromagnetic Theory

The Lorentz Force Law and the Faraday Tensor 239
The 4-Current 243
Doppler Effect 245
Maxwell's Equations 246
The Electromagnetic Plane Wave 248
The 4-Potential 250
Existence of Scalar and Vector Potentials in R^3 251
Exercises 253

Chapter 13. The Mechanics of Rigid Body Motion

Hamiltonian Systems and Equivalent Models 255
The Rigid Body 256
$O(3)$ and $SO(3)$ 256
Space and Body Representations 259
The Geometry of Rigid Body Motion 261
Left-Invariant 1-Form 263
Symmetry Group 264
Adjoint Representation 264
Momentum Mapping 265
Coadjoint Representation 266
Space Motions with Specified Momentum 266
Coadjoint Orbits and Body Motions 267

Special Properties of $SO(3)$ 271
Stationary Rotations 274
Classical Interpretation—Inertial Tensor, Principal Axes 274
Stability of Stationary Rotations 277
Poinsot Construction 280
Euler Equations 282
Phase Plane Analysis of Stability 283
Exercises 284

Chapter 14. Lie Groups

Lie Groups and Their Lie Algebras 286
Exponential Mapping 289
Canonical Coordinates 289
Subgroups and Homomorphisms 290
Adjoint Representation 291
Invariant Forms 292
Coset Spaces and Actions 293
Exercises 296

Chapter 15. Geometrical Models

Geometrical Mechanical Systems 297
Liouville's Theorem 298
Variational Principles 300
Forces 301
Fixed Energy Systems 304
Configuration Projections 305
Lorentz Force Law 306
Pseudomechanical Systems 306
Restriction Mappings 307
Rigid Body and Torque 308
Gauge Group Actions 310
Moving Frames and Goedesic Motion 311
Basic Theorem Local (Lemma 15.36) 314
Basic Theorem Global (Theorem 15.39) 316
Principal Bundle Model Using a Special Frame 319
The Souriau Equations 321
Structure of the Lie Algebra of the Lorentz Group 322
Construction of a Gauge Invariant 2-Form 322
Curvature Form 327
The Souriau GMS 328
Appendix: Conservation Laws 329
Exercises 332

Chapter 16. Principal Bundles and Connections; Gauge Fields and Classical Particles

Principal Bundles 335
Reduction of the Structural Group 337
Connections on Principal Bundles 337
Horizontal Lifts of Vectors 338
Curvature Form and Integrability Theorem 339
Horizontal Lifts of Curves 341
Associated Bundles 341
Parallel Transport 342
Gauge Fields and Classical Particles 342
Natural 2-Form on Coadjoint Orbits 343
Pseudomechanical System for Particles in a Gauge Field 345
Sternberg's Theorem 346
Geometrical-Mechanical System for Particles in a Gauge Field 347
Affine Group Model 349
Exercises 351

Chapter 17. Quantum Effects, Line Bundles, and Holonomy Groups

Quantum Effects 354
Probability Amplitudes 355
Probability Amplitude Phase Factors 355
DeBroglie and Feynman 356
Phase Factors and 1-Forms 356
COW and Bohm–Aharanov Experiments 358
Complex Line Bundles and Holonomy Groups 360
Integral Condition for Curvature Form 362
Bundle Description of Phase Factor Calculation 365
Remarks—Geometric Quantization 366
Holonomy and Curvature for General Lie Groups 367
Exercises 368

Chapter 18. Physical Laws for the Gauge Fields

Gauss's Law in Electromagnetic Theory 371
Charge Conservation 372
Curvature and Bundle-Valued Differential Forms 373
Covariant Exterior Derivative 375
Covariant Derivative of Sections and Parallel Transport 376
The Group of Gauge Transformations 377

The Killing Form 379
The Source Equation and Currents for Gauge Fields 379
Exercises 382

Bibliography 387
Index 389