

CONTENTS

1. REVIEW OF FINITE ELEMENT METHODS	1
Introduction	1
1.1 Basic Relationships	1
1.2 Basic Force Method	4
1.3 Basic Displacement Method	7
1.4 Analogous Displacement Method	7
1.5 Direct Stiffness Method	11
1.6 Combined Method I	14
1.7 Combined Method II	14
1.8 Combined Method III (Lagrange multipliers)	14
1.9 The Rank Technique	15
1.9.1 Investigation of linear equations	16
1.9.2 Jordan elimination procedure	17
1.9.3 Pivot selection	17
1.9.4 Investigation of equilibrium equations	18
1.10 Rank Force Method I	20
1.11 Rank Force Method II	20
1.12 Optimization of Redundancy Selection	21
1.12.1 Weighting procedures	22
1.12.2 Transformed equilibrium equations	23
1.12.3 Investigation of the transformed equilibrium equations	24
1.12.4 Transformed redundant flexibility matrix	24
1.12.5 Conditioning parameter	25
1.12.6 Numerical comparison of procedures	26
1.12.7 Main conclusions	31
1.13 Rank Force Method III	32
1.14 Eigen Force Method	35
1.14.1 Eigenvalue formulation of the static force method	35
1.14.2 Numerical example of force eigenvectors	41
1.15 Eigen Displacement Method	42
1.15.1 Eigenvalue formulation of the static displacement method	44

1.16	Comparison of the Eigen Force and Displacement Methods .	46
1.17	Stress Function Method	49
1.18	Further Basic Relationships	53
1.18.1	Assembled element flexibility–stiffness relations	53
1.18.2	Relationship between redundant and static element deformations	54
1.18.3	Assembled element force–deformation relationship corresponding to rearranged variables	56
1.19	Unified Force–Deformation Method	57
1.20	Matrix Deformation Method	59
1.21	Static Force Method	64
1.22	Structural Reactions and Internal Stress Distributions	65
1.22.1	Structural reactions	65
1.22.2	Internal stress distributions	67
2.	ELEMENT CHARACTERISTIC MATRICES AND INTER-CHANGEABILITY	68
	Introduction	68
2.1	Concept of Element Characteristic Matrices	68
2.2	The Strain Element	71
2.2.1	Force–deformation relation	71
2.2.2	Strain element assembly matrix	76
2.2.3	Strain element output matrix	77
2.3	The Stress Element	79
2.3.1	Force–deformation relation	79
2.3.2	Stress element assembly matrix	82
2.3.3	Stress element output matrix	85
2.4	Summary of Relationships and Identities	87
2.5	Element Interchangeability and its Practical Significance	87
2.6	Conventional Displacement Element Relations Using Characteristic Matrices	90
2.6.1	Using characteristic matrices of strain elements	90
2.6.2	Using characteristic matrices of stress elements	91
2.6.3	Summary	92
3.	CHARACTERISTIC MATRICES OF SOME STRAIN ELEMENTS	93
	Introduction	93
3.1	Constant Strain Axial Element	93
3.1.1	First and second characteristic matrices	93
3.1.2	Third characteristic matrix	96
3.1.3	Fourth characteristic matrix	98

3.1.4	Summary of strain element matrices	99
3.1.5	Interchangeability relations.	100
3.2	Straight Beam Element	100
3.2.1	First and second characteristic matrices	100
3.2.2	Third characteristic matrix	104
3.2.3	Fourth characteristic matrix	109
3.2.4	Summary of strain element matrices	109
3.3	Rectangular Isotropic Membrane Element	109
3.3.1	First and second characteristic matrices	109
3.3.2	Third characteristic matrix	115
3.3.3	Fourth characteristic matrix	120
3.3.4	Summary of strain element matrices	121
4.	CHARACTERISTIC MATRICES OF SOME STRESS ELEMENTS	122
	Introduction	122
4.1	Constant Stress Axial Element	122
4.1.1	First and second characteristic matrices	122
4.1.2	Third characteristic matrix	126
4.1.3	Fourth characteristic matrix	128
4.1.4	Summary of stress element matrices	128
4.1.5	Interchangeability relations.	129
4.2	Straight Beam Element	129
4.2.1	First and second characteristic matrices	129
4.2.2	Third characteristic matrix	132
4.2.3	Fourth characteristic matrix	138
4.2.4	Summary of stress element matrices	138
4.3	Rectangular Isotropic Membrane Element	139
4.3.1	First and second characteristic matrices	139
4.3.2	Third characteristic matrix	143
4.3.3	Fourth characteristic matrix	149
4.3.4	Summary of stress element matrices	150
5.	INCONSISTENT ELEMENTS AND THEIR CHARACTERISTIC MATRICES	151
	Introduction	151
5.1	Displacement Function Elements	152
5.1.1	Inconsistent force–deformation relationship	152
5.1.2	Assembly relationship for inconsistent elements	153
5.1.3	Output relationship for inconsistent elements	154
5.1.4	Automatic extraction of the zero strain (rigid body) modes	155
5.1.5	Characteristic matrices	157
5.1.5.1	First and second characteristic matrices	157

5.1.5.2	Third characteristic matrix	158
5.1.5.3	Fourth characteristic matrix	158
5.1.6	Summary of relationships and transformations	158
5.1.6.1	General inconsistent relations	158
5.1.6.2	Extraction process	158
5.1.6.3	Characteristic matrices from inconsistent relations	159
5.1.7	Demonstration of theory	159
5.1.7.1	Axial element	159
5.1.7.2	Beam element	167
5.2	Stress Function Elements	173
5.2.1	Inconsistent force–deformation relationship	173
5.2.2	Assembly relationship for inconsistent elements	175
5.2.3	Output relationship for inconsistent elements	176
5.2.4	Automatic extraction of the zero stress (rigid body) modes	176
5.2.5	Characteristic Matrices	178
5.2.5.1	First and second characteristic matrices	178
5.2.5.2	Third characteristic matrix	179
5.2.5.3	Fourth characteristic matrix	179
5.2.6	Summary of relationships and transformations	180
5.2.6.1	General inconsistent relations	180
5.2.6.2	Extraction process	180
5.2.6.3	Characteristic matrices from inconsistent relations	180
5.2.7	Demonstration of theory	180
5.2.7.1	Axial element	180
5.2.7.2	Beam element	189
5.3	Analogies in the Rigid Body Mode Extraction Processes	196
6.	ISOPARAMETRIC STRAIN ELEMENTS	198
Introduction		198
6.1	Isoparametric Strain Membrane Elements	200
6.1.1	Shape functions	201
6.1.2	Displacement functions	203
6.1.3	Stress and strain fields	204
6.1.4	Inconsistent force–deformation relationship	206
6.1.5	Assembly relationship	207
6.1.6	Output relationship	207
6.1.7	Demonstration of theory	207
6.2	Isoparametric Strain Solid Elements	211
6.2.1	Shape functions	213
6.2.2	Displacement functions	215
6.2.3	Stress and strain fields	215
6.2.4	Inconsistent force–deformation relationship	218
6.2.5	Assembly relationship	219

6.2.6	Output relationship	219
6.3	Isoparametric Strain Axial Elements	219
6.3.1	Shape functions	220
6.3.2	Displacement functions	220
6.3.3	Axial strain	221
6.3.4	Stress field	223
6.3.5	Incremental volume	223
6.3.6	Inconsistent force-deformation relationship	224
6.3.7	Assembly relationship	224
6.3.8	Output relationship	224
6.3.9	Demonstration of theory	225
7.	ISOPARAMETRIC STRESS ELEMENTS	228
	Introduction	228
7.1	Isoparametric Stress Plate-Bending Elements	228
7.1.1	Shape functions	228
7.1.2	Stress functions	229
7.1.3	Moment functions	230
7.1.4	Stress and strain fields	232
7.1.5	Distributed loads on curved boundaries	233
7.1.6	Kirchhoff loads on curved boundaries	234
7.1.7	Inconsistent force-deformation relationship	235
7.1.8	Assembly relationship	236
7.1.9	Output relationship	238
7.1.10	Demonstration of theory	238
7.2	Isoparametric Stress Solid Elements	248
7.2.1	Shape functions	248
7.2.2	Stress functions	249
7.2.3	Stress and strain fields	249
7.2.4	Inconsistent force-deformation relationship	253
7.2.5	Assembly relationship	254
7.2.6	Output relationship	255
7.3	Isoparametric Stress Axial Elements	255
7.3.1	Shape functions	255
7.3.2	Stress functions	255
7.3.3	Axial load	256
7.3.4	Stress and strain fields	257
7.3.5	Inconsistent force-deformation relationship	258
8.	FAMILY OF AXIALS AND SHEAR PANELS	259
	Introduction	259
8.1	Constant Load Axial Element with Constant Area	260
8.2	Linear Load Axial Element with Linear Area	260

8.2.1	First and second characteristic matrices	261
8.2.2	Third characteristic matrix	266
8.2.3	Fourth characteristic matrix	269
8.3	Four-Node Flat Rectangular Shear Panel	271
8.3.1	First and second characteristic matrices	271
8.3.2	Third characteristic matrix	274
8.3.3	Fourth characteristic matrix	277
8.4	Four-Node Warped Quadrilateral Shear Panel	277
8.4.1	First and second characteristic matrices	278
8.4.2	Third characteristic matrix	278
8.4.3	Fourth characteristic matrix	279
8.4.4	Demonstration of theory	279
8.4.4.1	Element vectors	279
8.4.4.2	Element natural flexibility matrix	280
8.4.4.3	Element assembly matrix	280
8.4.4.4	Element output matrix	280
8.5	Eight-Node Warped Quadrilateral Shear Panel	281
8.5.1	First and second characteristic matrices	282
8.5.2	Third characteristic matrix	282
8.5.3	Fourth characteristic matrix	289
8.5.4	Example to check element subroutine	292
8.5.4.1	Input information	292
8.5.4.1.1	Corner node coordinates	292
8.5.4.1.2	Section properties	292
8.5.4.1.3	Material properties	292
8.5.4.2	Element natural flexibility matrix	292
8.5.4.3	Element assembly matrix	293
8.5.4.4	Element output matrix	293
8.5.5	Check problems	294
8.5.5.1	Example 1	294
8.5.5.2	Example 2	294
8.6	Structural Sign Convention at Midside Nodes	298
9.	A CURVED BEAM ELEMENT IN THREE DIMENSIONS	300
	Introduction	300
9.1	Generalized Internal Forces	300
9.2	Element Natural Flexibility Matrix	302
9.3	Element Vectors and Parameters	304
9.4	Element Assembly Matrix	305
9.5	Element Output Matrix	307
9.6	Example to Check Element Subroutine	309
9.6.1	Input information	309
9.6.1.1	Nodal coordinates	309

9.6.1.2	Section properties	310
9.6.1.3	Material properties	310
9.6.2	Element natural flexibility matrix	310
9.6.3	Element assembly matrix	310
9.6.4	Element output matrix	311
9.7	Check Problem	311
10.	WARPED SEMI-MONOCOQUE QUADRILATERAL MEMBRANE ELEMENT	313
	Introduction	313
10.1	General Relationships	314
10.1.1	Element geometry	314
10.1.1.1	Geometrical definitions	314
10.1.1.2	Vector relationships	316
10.1.1.3	Nodal coordinates in oblique system	316
10.1.2	Anisotropic stress and strain relationships	317
10.1.2.1	Stress-strain relationships	317
10.1.2.2	Stress resultants	319
10.1.2.3	Stresses in basic skin and reinforcing members	320
10.1.3	Stress transformations	321
10.1.3.1	Oblique-Cartesian transformation of stress resultants	321
10.1.3.2	Rotation of Cartesian stresses	322
10.2	Element Natural Flexibility Matrix	323
10.3	Element Assembly Matrix	328
10.3.1	Equivalent nodal force vectors in projected plane	329
10.3.1.1	Force vectors for $N_{\bar{x}} = F_{\sigma 1}$	329
10.3.1.2	Force vectors for $N_{\bar{x}} = F_{\sigma 2} \bar{y}$	331
10.3.1.3	Force vectors for $N_{\bar{y}} = F_{\sigma 3}$	335
10.3.1.4	Force vectors for $N_{\bar{y}} = F_{\sigma 4} \bar{x}$	337
10.3.1.5	Force vectors for $N_{\bar{x}\bar{y}} = F_{\sigma 5}$	339
10.3.1.6	Summary of force vectors	342
10.3.2	Nodal force vectors due to warping	343
10.3.2.1	Moment unbalance due to $F_{\sigma 2}$	345
10.3.2.2	Moment unbalance due to $F_{\sigma 4}$	346
10.3.2.3	Correcting moment	346
10.3.2.4	Nodal forces for warping equilibrium	346
10.3.3	Assembly matrix	350
10.4	Element Output Matrix	351
10.4.1	Stresses in basic skin	351
10.4.2	Stresses in reinforcing members	352
10.4.3	Output matrix	352
10.5	Element Input Data	353
10.6	Example to Check Element Subroutine	353

10.6.1	Input information	353
10.6.1.1	Nodal coordinates (warped element)	353
10.6.1.2	Section properties	354
10.6.1.3	Material properties	354
10.6.2	Element natural flexibility matrix	355
10.6.3	Element assembly matrix	355
10.6.4	Element output matrix	355
10.7	Evaluation of Element	356
10.7.1	Evaluation criteria	356
10.7.1.1	Accuracy	356
10.7.1.2	Labour and computing costs	356
10.7.1.3	Range of applicability.	357
10.7.1.4	Geometric stability	357
10.7.2	Test problems and discussion	357
10.7.2.1	Panel with skew reinforcement	357
10.7.2.2	Single element test	359
10.7.2.3	Plane stress problems	359
11.	FAMILY OF CRACKED FINITE ELEMENTS	368
	Introduction	368
11.1	General Elastic Stress and Displacement Functions	369
11.1.1	Type I Westergaard functions	370
11.1.2	Type II Westergaard functions	370
11.1.3	General problems	371
11.2	Seven-Node Crack Element	371
11.2.1	Assumed ϕ -functions	371
11.2.2	Element characteristic matrices	373
11.2.2.1	Stress-strain relationship	374
11.2.2.2	Force-deformation relationship	374
11.2.2.3	Assembly relationship.	378
11.2.2.4	Output relationship	385
11.2.2.5	Example to check element subroutine	386
11.2.2.5.1	Input information.	386
11.2.2.5.2	Element natural flexibility matrix	387
11.2.2.5.3	Element assembly matrix	388
11.2.2.6	Check problem	389
11.3	Eleven-Node Crack Element	391
11.3.1	Assumed ϕ -functions	391
11.3.2	Element characteristic matrices	391
11.3.2.1	Force-deformation relationship	391
11.3.2.2	Assembly relationship.	391
11.3.2.3	Output relationship	396
11.3.2.4	Example to check element subroutine	396

11.3.2.4.1	Input information.	397
11.3.2.4.2	Element natural flexibility matrix	397
11.3.2.4.3	Element assembly matrix	398
11.3.2.5	Check problem	401
11.4	Symmetric Crack Element	403
11.4.1	Assumed ϕ -functions	403
11.4.2	Element characteristic matrices	404
11.4.2.1	Force–deformation relationship	404
11.4.2.2	Assembly relationship.	405
11.4.2.3	Output relationship	408
11.4.2.4	Example to check element subroutine	408
11.4.2.5	Check problem	408
12.	ANALYSIS OF LARGE PRACTICAL STRUCTURES USING SUBSTRUCTURE COUPLING PROCEDURES	409
	Introduction	409
12.1	The Substructure	413
12.2	Coupling of Substructures	416
12.3	Summary of Substructure Coupling Procedure	418
	REFERENCES	420
	INDEX	425