

Contents

Preface	vii
Preface to English edition	xi
List of main symbols	xii
Introduction	1
Chapter 1. Mathematical Models of Electrical Conductivity Ferromagnetic Elements with Eddy Currents	3
1.1. Statements of the Problem	5
1.2. Asymptotic Solution of Unsteady Boundary-Value Problems for Magnetic and Electrical Fields	8
1.3. Eddy Currents Mathematical Model	15
1.4. General Equations of System Dynamics with External and Eddy Currents and Mechanical Degrees of Freedom	18
1.5. Mathematical Models of Stabilized Ferromagnetic Elements as Objects of Control	20
1.6. Mathematical Models of the Electromagnetic Levitation System Actuator	24
Chapter 2. Mathematical Models of Stabilized Objects with Compartments Containing Vortex Low-Viscous Liquid	36
2.1. Mathematical Models of a Solid Body with Cavity Partially Filled with Ideal Liquid	37
2.2. Velocity Field of LV Liquid Vortex Motion in a Moving Cavity	48
2.3. Generalized Forces and Derivatives of Liquid Kinetic Energy with Respect to Generalized Velocities	53
2.4. The Mathematical Model of a Solid Body with a Cavity Containing Vortex Low-Viscous Liquid	58
2.5. Axially Symmetric Body. Particular Cases of General Equations of Perturbed Motion	63
2.6. Axisymmetric Body. Coefficients Conversion Formulae	66
2.7. Axisymmetric Body. Derivation of Equations of the Body - Liquid System Perturbed Motion from the Variational Principle	71
2.8. Spacecraft with LPRE Stabilized Attitude	78
2.9. Spacecraft with LPRE, Slowly Rotating around Its Longitudinal Axis	81
2.10. Determination of Hydrodynamic Coefficients	88
Chapter 3. Analytical and Numerical Methods of Dynamics Investigation of Vehicles Described by Vortex Models	97
3.1. Preliminary Remarks	98
3.2. Analytical Methods of Investigation. Harmonic Balance Method	99
3.3. An Algorithm for Numerical Solution of a Set of Integrodifferential Equations with a Singular Kernel of the Type $(t - \tau)^{-\sqrt{2}}$	109
3.4. Methodological Example	112
Chapter 4. Experimental Verification of Mathematical Models for Eddy Currents and Vortex Motions of Liquid	123
4.1. Mathematical Models Used for Experimental Data Processing	123
4.2. Determination of Mathematical Model Parameters Based on Experimental Results	126
4.3. Scheme of the Experiment and Primary Processing of Results	130
4.4. Verification of Models for Eddy Currents in HECF Elements	133
4.5. Low-Viscous Liquid Vortex Motions Model Verification	144

Chapter 5. Some Dynamics Problems for Systems with Electromagnetic Actuators	156
5.1. Characteristic Properties of Electromagnet as an Object of Control. Requirements to the Air Gap Regulation System.....	157
5.2. Mathematical Model of the Two-Mass System 'Controlled Electromagnet - Mass with Elasto-Viscous Suspension'	159
5.3. Measurements Composition Influence on Required Completeness of Controlled Electromagnet Mathematical Model	163
5.4. Eddy Currents Influence on Closed-Loop System Dynamics. Reduction of Integrodifferential Equations to an Equivalent Set of Differential Equations	168
Chapter 6. Some Dynamics Problems for a Spacecrafts Having Compartments Partially Filled with Liquid	174
6.1. Stabilizability and Dynamic Stability of Spacecrafts Having Compartments Partially Filled with Liquid	175
6.2. Simplified Mathematical Models of Perturbed Motion for a Spacecraft Having Compartments Partially Filled with Liquid	182
6.3. Self-Sustained Oscillations in the Closed-Loop System 'Spacecraft - Liquid - Controller'	186
6.4. SC Stability in the Yaw Plane with Account of Potential and Vortex Motions of Liquid in Tanks	197
6.5. SC Stability in the Roll Plane for Non-Small Amplitudes of Angular Oscillations	206
Chapter 7. Examples of Control Law Synthesis for an Object Described by a Vortex Model	214
7.1. A Control Law Allowing Hardware Implementation, Based on Air Gap Sensor and Current Transducer Indications.....	215
7.2. Synthesis of a Relay-Controller Closed-Loop System	223
7.3. Mathematical Modelling of Electromagnetic Levitation System Dynamics	233
Chapter 8. Some Dynamics Problems for a Solid Body with Electrically Conductive Liquid Moving in Magnetic Field	245
8.1. Statements of the Problem. Main Assumptions.....	246
8.2. Magnetic Hydrodynamics Boundary-Value Problems for LVECF Liquid	248
8.3. Liquid - Magnetic Field System Kinetic Energy. Generalized Forces and Generalized Voltages.....	252
8.4. Equations of Dynamics for a Solid Body Containing LVECF Liquid with Related Magnetic Field Presence	255
8.5. Equations of Dynamics for a Solid Body with a Cavity of Revolution Having Narrow Internal Ribs.....	261
8.6. The Case of a Circular Cylinder-Shaped Cavity.....	264
8.7. Magnetic Field Influence on Solid Body - LVEC Liquid Open-Loop System Frequency Response	272
8.8. The Possibility of Using Magnetohydrodynamic Effects to Ensure Dynamic Stability of Spacecraft.....	284
Conclusion.....	286
Bibliography	287
Index	293