

CONTENTS

<i>Foreword</i>	ix
<i>Preface</i>	xi
<i>Glossary</i>	xxiii

PART ONE FUNDAMENTALS OF INTEGRATED CIRCUIT DESIGN

1. Introduction to Integrated Circuits	3
1-1 Perspective	4
Economics 5; Reliability 6; Performance 7	
1-2 Qualitative Description of Fabrication Processes	8
The Monolithic Single-crystal Approach 8; Dielectric Isolation 10; The Thin-film Approach 10; Hybrid Integrated Circuits 11	
2. Fabrication Constraints and General Design Guidelines	12
2-1 Fabrication of a Single-crystal Monolithic Circuit	12
Photo Resist and Oxide Masking 13; Diffusion 14; Epitaxy 15; Metallization 15	
2-2 Components of Single-crystal Monolithic Circuits	15
Transistors 15; Diffused Resistors 18; Capacitors 18	
2-3 Single-crystal Monolithic Circuit Fabrication Steps	20
2-4 Compatible Thin-film Circuits	24
2-5 Monolithic Circuits Using Dielectric Isolation	26
2-6 Multiple-chip Hybrid Circuits	28
2-7 Parasitic Effects in Integrated Circuits	29
p-n Junctions 29; Diffused Resistors 29; Metal-oxide-silicon Capacitors 30; Monolithic Transistors 30; Dielectrically Isolated and Hybrid Transistors 30; Active Parasitics: Parasitic Transistor Action in Monolithic Circuits 30	
2-8 General Design Guidelines	31
Monolithic Single-crystal Circuits 31; Compatible Thin-film Techniques 32; Dielectric Isolation 32; Hybrid Circuits 32; Summary 33	
2-9 Circuit Design Guidelines	33
Monolithic Circuits 33; Hybrid Circuits 33	
2-10 Layout Design Guidelines	34
Monolithic Circuits 34; Hybrid Circuits 34	
REFERENCES 35	
3. Survey of Large-signal Transistor Models	36
3-1 Commonly Used Transistor Models	36
3-2 The Mathematical Model	38
Basic Equations 38; Junctions 40	

3-3	The Uniform-base Transistor	41
	The Mathematical Model 41; Regions of Operation 42; A Direct Solution for the Base Region 43	
3-4	The Ebers-Moll Model	45
	The Active Region 45	
3-5	The Charge-control Model	48
3-6	The Lumped Model	50
3-7	Junction Capacitances	51
3-8	Comparison of Models for the Uniform-base Transistor	53
3-9	Introduction to the Nonlinear Model	54
	REFERENCES 57	
4.	The Nonlinear Transistor Model	58
4-1	Introduction	58
4-2	Assumptions and Approximations	60
4-3	Analysis of the Base Region	63
	The Continuity Equation 63; The Built-in Field 64; Solution of the Continuity Equation 65; The Junction Currents 65	
4-4	Analysis of the Collector Region	67
4-5	The Complete Solution for the Two-junction Transistor	68
	Some Properties of the Two-junction Model 69; Short-circuit Current Gains 70	
4-6	Simplification of the Frequency Dependence of the Transistor Model	70
	Distribution of the Poles and Zeros 71; Taylor Expansions 71; The Approximate Model 72; Nature of the Approximations 74	
4-7	Multijunction Devices	75
	The Three-junction n-p-n-p Transistor 75; The Lateral p-n-p Transistor 78	
4-8	Frequency Dependence of the Transistor	79
4-9	The Piecewise Linear and Small-signal Models	85
	The Piecewise Linear Junction V-I Relations 85; The Piecewise Linear Model 88; The Small-signal Model 89; Discussion of the Piecewise Linear Model 89	
4-10	Measurement of Nonlinear Model Parameters	94
	DC Measurements 95; Measurement of the Time Constants of the Nonlinear Model 95	
4-11	Summary	101
	REFERENCES 102	
5.	Parasitic Effects in Integrated Circuits	103
5-1	Junction Capacitors	104
5-2	Diffused Resistors	107
	Average Capacitance of the Diffused Resistor 108; Solution for the Diffused Resistor 109; Lumped Approximations for the Diffused Resistor 111	
5-3	Metal-oxide-silicon Capacitors	113
5-4	Passive Parasitics of Transistors for Monolithic Single-crystal Integrated Circuits	114
	Collector Resistance 116; Substrate Resistance 122; Collector-substrate Capacitance 122; Sample Calculation of Collector Parasitics 123; Simplification of the Collector Parasitic Model 126	
5-5	Parasitics for Transistors in Hybrid and Dielectrically Isolated Integrated Circuits	126

	<i>Contents</i>	xvii
5-6 Active Parasitics: Parasitic Transistor Action		127
5-7 Summary		130
REFERENCES		131

PART TWO INTEGRATED LOGIC CIRCUITS

6. Terminal Parameter Characterization of Logic Circuits	135
6-1 Logic Functions	136
6-2 Circuit Implementation of Logic Operations	137
Emitter-coupled Logic (ECL) 137; Direct-coupled Transistor Logic (DCTL)	
138; Diode-transistor Logic (DTL) 140; Transistor-transistor Logic (T ² L)	
141; Memory Circuits: The Flip-flop 142	
6-3 Logic Circuit Characterization	143
DC Terminal Parameter Characterization 145; Analysis Techniques 150;	
Characterization of the Transient Response 151	
6-4 Performance Evaluation	151
Operating Points 151; Logic Swing, Threshold Point, Unity Gain Points,	
and Transition Width 154; Noise Margin, Noise Sensitivity, and Noise Im-	
munity 154; Worst-case Characteristics 156; Power Dissipation 157; Tran-	
sient Properties 157; Power-Delay Time Product 158	
6-5 Summary	158
REFERENCES	158
7. Emitter-coupled Logic	159
7-1 Emitter-coupled Logic Gate and Its Equivalent Circuit	159
7-2 DC Characteristics of the ECL Gate	162
Transfer Characteristics 162; Noise Sensitivity, Noise Margins, and Transi-	
tion Width 166; Worst-case Transfer Characteristics 168; Input Character-	
istic 171; Output Characteristics 172	
7-3 Power Dissipation	173
7-4 Transient Analysis	174
Input Capacitance and the Base Response 175; Collector Capacitance 179;	
Collector Response 181; Emitter-follower Response 186	
7-5 Design Optimization	188
Total Switching Time 188; Design Equations 188	
7-6 Design Example	191
Input Capacitance (Depletion Layer Component) 191; Collector Capaci-	
tance 192; Power Division (First Iteration) 193; Parasitic Capacitance of	
R_{c1} and R_e (First Iteration) 193; Final Design 194; Delay Time 194	
7-7 ECL Gate Modifications	195
7-8 Conclusions	198
REFERENCES	199
GENERAL REFERENCES	199
8. Direct-coupled Transistor Logic	200
8-1 Integrated DCTL Layout Considerations	201
Active Parasitics 203; Passive Parasitics 204	
8-2 Nonlinear DC Analysis of DCTL	207
Inverter Characteristics 208; DCTL Characteristics 211	

8-3	Piecewise Linear Analysis	213
	General Procedure 214; Breakpoints 215; Approximations 216; Breakpoint Equations 219; Piecewise Linear Characteristics 221	
8-4	Transient Analysis	222
	Turn-on Transient 224; Turn-off Transient 231	
8-5	Integrated DCTL Design Considerations	237
	Logic Swing and Transition Width 238; Noise Margins 239; Worst-case Considerations 240; Maximum Fan-out 241; Power-Delay Product 245	
8-6	Summary	245
9.	Diode-Transistor Logic	246
9-1	Diodes for Integrated Circuits	248
	Multilayer Diode Configurations 249; DC Diode Characteristics 249; Parasitic Transistor Action 251; Forward Voltages 251; Diode Capacitance 255; Diode Storage Times 255; Reverse Breakdown Voltages 256; Choice of DTL Diodes 256	
9-2	Integrated DTL Layout Considerations	258
	Active Parasitics 259; Passive Parasitics 260; Fabrication of the Input Diode Cluster 260; Additional Parasitics in the Input Cluster 264; Offset Diode, Resistor, and Transistor Parasitics 264	
9-3	Nonlinear DC Analysis of DTL	267
9-4	Piecewise Linear Analysis	272
	Breakpoints 273; Approximations 273; Breakpoint Currents and Voltages 275	
9-5	Transient Analysis	279
	Turn-on Time Constants 280; Diode and Transistor Approximations 280; Turn-on Transient 281; Turn-off Transient 283	
9-6	DTL Design Considerations	286
	Logic Swing and Transition Width 286; Noise Margins 286; Worst-case Considerations 287; Maximum Fan-out 287; Power-Delay Product 287	
9-7	Modification of the DTL Gate	288
9-8	Summary	290
	REFERENCES 290	
10.	Transistor-Transistor Logic	291
10-1	Integrated T ² L Layout Considerations	291
	Active Parasitics 293; Passive Parasitics 294	
10-2	Nonlinear DC Analysis of T ² L	294
	T ² L Characteristics 294; Current Hogging in T ² L 296	
10-3	Piecewise Linear Analysis	301
10-4	T ² L Transient Analysis	305
	Turn-on Transient 306; Turn-off Transient 308	
10-5	T ² L Design Considerations	310
10-6	Modification of the T ² L Gate	312
10-7	Summary	313
11.	Comparison of Integrated Logic Circuits	315
11-1	Comparison of DC Terminal Parameter Characteristics	315
	Inverse Transfer Characteristics 321	

11-2	DC Transfer and Power-supply Characteristics of Monolithic Single-crystal Digital Circuits	323
11-3	Tabulation of DC Properties	326
11-4	Comparison of Transient Characteristics for Integrated Logic Gates	331
11-5	Tabulation of Delay Times	336
11-6	Noise in Integrated Digital Systems	341
	Crosstalk—Lumped Parameter Approach 342; Experimental Results (Lumped Parameter Approach) 344; Crosstalk—Distributed Parameter Analysis 348; Experimental Results for the Distributed Case 351; Power-supply Noise 356; Externally Generated Noise 357	
11-7	Concluding Remarks on Digital Integrated Circuits	360
	Ultrahigh Speed Range 361; High Speed Range 362; Medium Speed Range 362; Low Power Range 363	
	REFERENCES 364	

PART THREE LINEAR INTEGRATED CIRCUITS

12.	Small-signal Characterization of Integrated Transistors	367
12-1	The Small-signal Model of the Integrated Transistor	367
	Conventional Small-signal Model 368; AC Current Crowding 371; Conditions for Which AC Crowding Affects Performance 373	
12-2	Two-port Gain and Stability Functions	374
	Unilateral Power Gain 375; Invariant Stability Factor 375; Maximum Frequency of Oscillation 376; Maximum Available Power Gain and Gain-stability Product 376; Available Power Gain and Transducer Gain 377	
12-3	Gain and Stability Functions of the Integrated Transistor	379
	Unilateral Power Gain and Maximum Frequency of Oscillation 379; Stability Factors 382; Gain-stability Product and Maximum Available Gain 385	
12-4	Noise in Integrated Circuit Transistors	385
	Integrated Transistor Noise Model 386; Single-stage Noise Figures 388; Comparison of Single-stage Noise Figures 389; Optimum Single-stage Noise Figures 391	
12-5	Noise Performance of Integrated Two-stage Cascades	391
	Cascade Noise Figures 392; Optimum Cascade Noise Figures 394; Comparison of Optimum Cascade Noise Figures 395; Transformer Coupling 397	
12-6	Summary	398
	REFERENCES 399	
13.	DC and Differential Amplifiers	400
13-1	Differential Amplifiers	401
13-2	Advantages of Integrated Transistor Pairs	402
13-3	Differential Amplifier Analysis	403
	Analysis Procedure 403; Analysis of the Balanced Amplifier 405; Extension to Unbalanced Circuits 406	
13-4	Frequency Performance of the Differential Amplifier	408
13-5	Noise in the Differential Amplifier	409
13-6	Comparison of Integrated and Discrete Differential Amplifiers	410
13-7	Modification of the Basic Differential Amplifier	412
13-8	Layout Considerations	414

xx Contents

13-9	Summary	415
	REFERENCES 415	
14.	High-frequency Tuned Amplifiers	416
14-1	Broadband Amplifier Design.	416
	Noise Figure 417; Gain and Stability 418; Choice of Circuit Configuration 418; Analysis of the Cascode Stage 419; Biasing and AGC 421	
14-2	Design of an IF Amplifier	422
	IF Stage Design 422; Layout of the IF Stage 423; Detector and Video Amplifier 424; Packaging 427; Complete IF Amplifier Assembly 427; Performance of the IF Amplifier 428	
14-3	Narrow-band Amplifier Design	430
	Design Procedure 430; Graphical Design Procedure 433; Load Admittance 440; Input Admittance 441; The Linvill Charts 443	
14-4	Narrow-band Amplifier Design Examples	444
	Circuit Configuration 444; Automatic Gain Control 447; Evaluation of the Small-signal Performance 447; Design of a 120-Mc Amplifier 450; Bandwidth 453; A 200-Mc Amplifier Design Example 456	
14-5	Summary	458
	REFERENCES 458	
15.	Frequency Selective Amplification without Inductors	460
15-1	Active RC Networks	461
	Negative Immittance Converters 461; Gyrators 463; Networks with Controlled Sources 465	
15-2	RC Active Networks Using Unity-gain-controlled Sources.	466
15-3	The Digital Filter	470
15-4	Summary	472
	REFERENCES 475	
16.	Retrospect and Prospect	476
16-1	Summary	476
	DC and Low-frequency Amplifiers 477; Bandpass Amplifiers 477	
16-2	The Impact of Integrated Circuits upon System Packaging and Design . . .	478
	System Packaging 478; System Design 485	
16-3	Integrated Circuit Network Theory	485
16-4	Theoretical Limits of the Physical Size of Microcircuits	486
16-5	Integrated Circuits and Neurons	487
	REFERENCES 491	
APPENDIX A	Derivation of the Ebers-Moll, Charge-control, and Lumped Models	492
APPENDIX B	Common Emitter Current and Saturation Effects for Emitter-coupled Logic	509
APPENDIX C	Single Exponential Approximations for the Piecewise Linear Transient Analysis.	514
APPENDIX D	Measurement Techniques for Digital Integrated Circuits	523

APPENDIX E	Comparison of the Cascade Noise Figures	532
APPENDIX F	Controlled Sources and Nonoptimum Networks	536
<i>Problems</i>		540
<i>Index</i>		573