Contents

Preface ix

Glossary of Mathematical Notation xi

PART I FOUNDATIONS OF MECHANICS
This part is an extension of joint work with G. Caratú

Chapter 1 Introduction to Part I. 3

Chapter 2 A Digression on Manifolds and Diffeomorphisms 7

Chapter 3 Construction of Q: From Observables to the Configuration Space Manifold 14
3.1 Construction of the configuration space Q 15
3.2 Topological and differential nature of Q 17
3.3 Invariants of a system under Q transformations 20

Chapter 4 Time and Transformations on Time. 24

Chapter 5 A Digression on Calculus on Manifolds, Bundles, Vector Fields and Forms. 28
5.1 Bundles. 28
5.2 Vector fields 34
5.3 Forms 39
5.4 The Lie derivative 43
5.5 Vector fields as generators of transformations 47

Chapter 6 From Trajectories to the Vector Field 49

Chapter 7 Lifting to a Carrier Space: Canonical Lifting. 64

Chapter 8 A Digression on Submanifolds and Smooth Maps. . . . 78

8.1 Submanifolds from imbeddings 79
8.2 Submanifolds from submersions 83

Chapter 9 Transformations on TQ. 85

Chapter 10 Integrating the Dynamics on TQ. Hamiltonian and Lagrangian Formalisms 90
10.1 Integrating the dynamics 90
10.2 Simple reduction of Hamiltonian dynamics. 97
10.3 Existence of symplectic forms on TQ 104
10.4 The Lagrangian formalism 107
10.5 Other classes of dynamical systems 109
Appendix. 112

Chapter 11 From the Tangent Bundle to the Cotangent Bundle. . . 115
11.1 The fiber derivative 115
11.2 Lifting vector fields from Q to T^*Q 120

Chapter 12 The Canonical Hamiltonian Formalism on T^*Q 122
12.1 Dynamics on T^*Q 122
12.2 Examples 124
12.3 Functions in involution. 127

Chapter 13 Equivalent Lagrangians and Hamiltonians 128
13.1 Ambiguity on TQ. 128
13.2 Ambiguity on T^*Q 133

Chapter 14 Other Carrier Spaces: Action-Angle Variables and the Hamilton–Jacobi Method. 137
14.1 Action-angle variables 138
14.2 The Hamilton–Jacobi method. 144

Chapter 15 The Noether Theorem 151
15.1 The Hamiltonian formalism 151
15.2 The Lagrangian formalism 153
15.3 On the converse of the Noether theorem 161

Appendix to Part I: Time-dependent Hamilton dynamics. 166

PART II REDUCTION, ACTIONS OF ALGEBRAS AND GROUPS

Chapter 16 Introduction to Part II 173

SECTION A REDUCTION

Chapter 17 Linear Dynamical Systems: A Prelude to Reduction. . . 177

17.1 Reduction by a constant of the motion (Hamiltonian system) . 177
17.2 Simpler reduction of the same system 181
17.3 Reduction of linear systems 182

Chapter 18 A Digression on Foliations and Distributions 186
18.1 Foliations 186
18.2 Distributions 194
18.3 Foliations and additional structure 199

Chapter 19 Reduction of Dynamical Systems through Regular Foliations 203
19.1 Projectability 203
19.2 Reduction through foliation 209
19.3 Remarks on integrating the dynamics on M 212

Chapter 20 Foliation of Symplectic Manifolds and Reduction of Hamiltonian Systems 219
20.1 Distributions on symplectic manifolds, function groups . . . 219
20.2 Foliations generated by submersions 221
20.3 Reduction of Hamiltonian systems 227

SECTION B ALGEBRA AND GROUP ACTIONS

Chapter 21 A Digression on Lie Algebras and their Actions on Manifolds 235
21.1 Introduction: distributions and Lie algebras 235
21.2 Lie algebras 238
21.3 Actions of Lie algebras on manifolds 241
21.4 The connection between Lie algebra actions and dynamics . . 249

Chapter 22 Actions of Lie Algebras on Symplectic Manifolds 252
22.1 Symplectic, Hamiltonian, and other actions 253
22.2 Introduction to the momentum map 258
22.3 The momentum map: details and examples 262
22.4 The existence of Hamiltonian actions 268
22.5 Symplectic forms on $\mathfrak{G}^*$ and Poisson brackets 272
22.6 A detailed example: the Kepler problem 273

Chapter 23 A Digression on Lie Groups and their Actions on Manifolds 277
23.1 Lie groups 278
23.2 Foliations and subgroups of $GL(n, \mathbb{R})$ 282
23.3 Lie groups and Lie algebras 285
23.4 Actions of Lie groups on manifolds 287
23.5 Relation between the actions of Lie groups and the actions of Lie algebras 291

23.6 Examples of Lie group actions 294

Chapter 24 Actions of Lie Groups on Symplectic Manifolds 304
24.1 Lie group actions which preserve differential forms 304
24.2 Reduction with symplectic actions: the momentum map . . . 309
24.3 Reduction on T^*Q. Dynamics 312

Chapter 25 Parallelizable Manifolds. Dynamics on Lie Groups . . . 317
25.1 Calculus on parallelizable manifolds 317
25.2 Explicit construction of parallelizations 319
25.3 Formalisms of dynamics of TG and T^*G 323
25.4 The rigid rotator 325

Chapter 26 Examples and Applications 330
26.1 The harmonic oscillator in n degrees of freedom 330
26.2 The nonrelativistic spinning particle 334
26.3 The electron–monopole system 336
26.4 Relativistic interacting particles 339
26.5 Action-angle variables and Hamilton–Jacobi: a second look with Lagrangian foliations 344
26.6 Uniqueness of the Lagrangian 349
26.7 Dynamical systems with constraints 352

Conclusion 355

References 358

Further reading 362

Index 371