

CONTENTS

PREFACE	v
GENERAL INTRODUCTION <i>by Eugene P. Wigner</i>	xi
CHAPTER 1. INTRODUCTION	1
CHAPTER 2. ABSTRACT GROUPS	4
2.1 Abstract groups	5
2.2 Subgroups and factor groups	7
2.3 Homomorphisms	9
2.4 Some further aspects of groups	10
CHAPTER 3. LIE GROUPS	13
3.1 Lie groups	14
3.2 Compact groups	17
3.3 Locally isomorphic groups	18
3.4 Properties of the product functions	18
3.5 One-parameter subgroups	20
3.6 Canonical coordinates	23
3.7 One-parameter subgroups of matrix groups	26
CHAPTER 4. LIE ALGEBRAS	27
4.1 Abstract definition of a Lie algebra	27
4.2 Lie algebra of a matrix group	30
4.3 An example	32
4.4 The Jacobi identity	34

4.5	Subalgebras and factor algebras	36
4.6	Relations between Lie groups and their algebras	39
4.7	Some important Lie algebras	41
4.8	Lie algebras of dimension 1, 2, and 3	43
CHAPTER 5. INVARIANT INTEGRATION		50
5.1	Integration on a finite group	50
5.2	Integration on a compact Lie group. The Hurwitz integral	51
5.3	Right invariant integration	57
CHAPTER 6. GROUP REPRESENTATIONS		61
6.1	Group representations	62
6.2	Unitary representations	65
6.3	Reducibility of representations	67
6.4	Examples of representations	70
6.5	Schur's Lemma	71
6.6	Orthogonality properties of irreducible representations	73
6.7	Group characters	76
6.8	Direct product of representations	78
6.9	Representations in function spaces	80
6.10	Representations of Lie algebras	83
CHAPTER 7. COMPLETENESS THEOREMS FOR GROUP REPRESENTATIONS		89
7.1	Completeness theorems for finite groups	89
7.2	The Peter-Weyl theorem	92
7.3	Infinite-dimensional representations of a compact Lie group	102
CHAPTER 8. THE GROUPS $U(1)$ AND $SU(2)$		108
8.1	Rotation in the plane	108
8.2	Representations of the group $SU(2)$	110
8.3	Reduction of the direct product of irreducible representations	116
8.4	Symmetry and other properties of the 3-j coefficients	121
8.5	Special 3-j coefficients	123
8.6	Reduction of a threefold product	124
CHAPTER 9. ROTATIONS IN SPACE		130
9.1	General properties of the rotation group	130
9.2	The functions of v^{α}_{β} and invariant integration	137
9.3	The homomorphisms of $SU(2)$ onto $O(3)^+$	140

Contents	ix
9.4 Representations of the rotation group	143
9.5 Harmonic polynomials and representations of $O(3)^+$	146
9.6 Differential equations for the group representations	151
9.7 Properties of the functions d^l_{mn}	157
9.8 Properties of spherical harmonics	164
CHAPTER 10. ROTATION IN FOUR DIMENSIONS	169
10.1 The Lie algebra of $O(4)$	169
10.2 Parametrization of $O(4)^+$ as a direct product	170
10.3 Representations of $O(4)^+$	172
10.4 The functions $H_{j,K}$	176
10.5 Properties of Gegenbauer polynomials	178
10.6 Spherical harmonics in four dimensions	183
CHAPTER 11. EUCLIDEAN GROUP IN THE PLANE	189
11.1 Properties of the group E_2	190
11.2 The Frobenius method of induced representations	192
11.3 Representations of E_2	197
11.4 Representations of the Lie algebra of E_2	199
11.5 Properties of Bessel functions	202
11.6 The method of contraction	206
11.7 Partner functions for the representations Δ_p	209
CHAPTER 12. THE EUCLIDEAN GROUP IN SPACE	215
12.1 Representations of E_3 by the Frobenius method	215
12.2 Explicit construction of the representations of E_3	220
12.3 Properties of the spherical Bessel functions	225
12.4 Spherical Neumann and Hankel functions	229
12.5 Appendix	233
CHAPTER 13. THE QUANTUM-MECHANICAL GROUP	234
13.1 The quantum-mechanical group	234
13.2 Properties of Laguerre polynomials	240
13.3 Harmonic oscillator wave functions	245
REFERENCES	251
INDEX	255