



# CONTENTS

PREFACE . . . . .	v
SPECIAL ABRIDGED NOTATIONS . . . . .	vii
INTRODUCTION . . . . .	1
 <b>Chapter One. Introductory Treatment of Dimensions One and Two</b>	
§1. The Characteristic Function . . . . .	5
§2. Systems of Dimension Unity. Direct Control . . . . .	7
§3. System of Dimension Unity. Indirect Control . . . . .	8
§4. System of Order Two . . . . .	13
 <b>Chapter Two. Indirect Controls</b>	
§1. Vectors and Matrices . . . . .	17
§2. Indirect Control. General Type . . . . .	18
§3. Comparison with a Recent Result of Yacubovich . . . . .	22
§4. On the Utilization of Certain Complex Coordinate Systems . . . . .	23
§5. Special Cases . . . . .	24
 <b>Chapter Three. Indirect Controls (Continued)</b>	
§1. Invariance under Change of Coordinates . . . . .	27
§2. Reduction of the Number of Conditions on the Control Parameters . . . . .	28
§3. Lurie's Method and a Variant . . . . .	31
§4. Application to Systems of Order Two . . . . .	33
 <b>Chapter Four. Direct Controls. Linearization Multiple Feedback</b>	
§1. Direct Control: General Case . . . . .	39
§2. Direct Control, Standard Example . . . . .	41
§3. Reduction of an Indirect Control to a Special Direct Control . . . . .	42
§4. Linearization of Direct Controls . . . . .	43
§5. Linearization of Indirect Controls . . . . .	46
§6. Direct Control with Matrices $B$ or $C$ of Rank $< n$ . . . . .	48
§7. Direct Controls with Matrices $B, C$ , of Rank $n - 1$ . . . . .	50
§8. Direct Control Whose Matrix $A$ Has Zero as a Characteristic Root (Kenneth Meyer) . . . . .	51
§9. Direct Control Whose Matrix Has a Pair of Conjugate Pure Imaginary 'Characteristic Roots (Kenneth Meyer) . . . . .	55
§10. Multiple Feedbacks . . . . .	56

CONTENTS

**Chapter Five. Systems Represented by a Set of Equations of Higher Order**

§1. Generalities . . . . .	61
§2. A Digression on Linear Systems . . . . .	62
§3. Indirect Control . . . . .	64
§4. Indirect Control: An Example . . . . .	67
§5. Direct Control . . . . .	70

**Chapter Six. Discontinuous Characteristics**

§1. Continuous Approximation of Discontinuous Characteristics . . . . .	72
§2. Direct Discussion of Discontinuities . . . . .	73
§3. Some Examples . . . . .	79
§4. Special Switching Lines . . . . .	84
§5. Multiple Feedback Switching Line . . . . .	85
§6. Complementary Remarks . . . . .	86

**Chapter Seven. Some Recent Results of V. M. Popov**

§1. Generalities. The Theorems of Popov . . . . .	87
§2. Preliminary Properties . . . . .	91
§3. Proof of Popov's First Theorem . . . . .	93
§4. The Generalized Liapunov Function of Popov . . . . .	98
§5. Proof of Popov's Second Theorem . . . . .	100
§6. Comparisons . . . . .	101
§7. On the Function $G(z)$ as Transfer Function . . . . .	104
§8. Direct Control . . . . .	105
§9. Conclusion . . . . .	105

**Chapter Eight. Some Further Recent Contributions**

§1. Controllability and Observability . . . . .	107
§2. Reduction of the System to One with a Completely Controllable Pair $(A, b)$ and Completely Observable Pair $(c', A)$ . . . . .	109
§3. A Special Form for Systems with Completely Controllable Pair $(A, b)$ . . . . .	113
§4. Main Lemma (Yacubovich and Kalman) . . . . .	114
§5. Liapunov–Popov Function and Popov Inequality . . . . .	118
§6. Fundamental Theorem . . . . .	119
§7. A Recent Result of Morozan . . . . .	121
§8. Return to the Standard Example . . . . .	122
§9. Direct Control . . . . .	123
§10. Résumé (Indirect Control: $\gamma > 0$ ) . . . . .	124
§11. Complement on the Finiteness of the Ratio $\varphi(\sigma)/\sigma$ . . . . .	125

## CONTENTS

### **Chapter Nine. Miscellaneous Complements**

§1. The Jordan Normal Form for Real or Complex Matrices . . . . .	128
§2. On a Determinantal Relation . . . . .	132
§3. On Liapunov's Matrix Equation . . . . .	133
§4. Liapunov and Stability . . . . .	136
Appendix A: An Application of Multiple Feedback Control . . . . .	139
Appendix B: An Example from the Theory of Nuclear Power Reactors (Kenneth Meyer) . . . . .	142
BIBLIOGRAPHY . . . . .	144
INDEX . . . . .	149