CONTENTS

PREFACE v

ACKNOWLEDGMENTS vii

LIST OF SYMBOLS ix

PART A INTRODUCTION AND BACKGROUND MATERIAL 1

1 INTRODUCTION 3

1-1 Background and applications 3
1-2 General description of the method 5
1-3 Summary of the analysis procedure 10
1-4 Fundamentals for the understanding of the method 15
References 16
Further reading 17

2 MATRIX TECHNIQUES 18

2-1 Matrix notation 18
2-2 Solution of large systems of algebraic equations 19
2-3 Eigenvalue problems 22
2-4 Solution of propagation problems 24
References 26
Further reading 28

3 BASIC EQUATIONS FROM SOLID MECHANICS 29

3-1 Stress 29
3-2 Strain and kinematics 30
3-3 Linear constitutive equations 32
3-4 Two-dimensional specializations of elasticity 35
3-5 Nonlinear material behavior 41
3-6 Material characterization 49
References 50
Further reading 51

4 VARIATIONAL METHODS **52**

4-1 Calculus of variations 52
4-2 Variational principles of solid mechanics 57
4-3 Applications to the finite element method 61
References 62
Further reading 62

PART B THE THEORY OF THE FINITE ELEMENT METHOD **65**

5 THE BASIC COMPONENT—A SINGLE ELEMENT **67**

5-1 The concept of an element 67
5-2 Various element shapes 72
5-3 Displacement models 77
5-4 Isoparametric elements 88
5-5 Element stresses and strains 102
5-6 Direct formulation of element stiffness and loads 106
5-7 Variational formulation of element stiffness and loads 113
5-8 Consistent loads vs. lumped formulation 124
5-9 Condensation of internal degrees of freedom 125
5-10 Summary and examples 126
References 148
Further reading 150
Exercises 150

6 THE OVERALL PROBLEM—AN ASSEMBLAGE OF ELEMENTS **154**

6-1 Discretization of a body or structure 154
6-2 Mesh refinement vs. higher order elements 173
6-3 Interconnections at nodes 176
6-4 Effect of displacement models on interelement compatibility 178
6-5 Construction of stiffness matrix and loads for the assemblage 181
6-6 Boundary conditions 190
6-7 Solution of the overall problem 194
6-8 Examples 198
References 206
Further reading 210
Exercises 210

7 TECHNIQUES FOR NONLINEAR ANALYSIS **215**

7-1 Initial strains 215
7-2 Nonlinear problems 217
7-3 Basic nonlinear solution techniques 219

7-4 Computer aspects of nonlinear techniques 227
7-5 Problems involving material nonlinearity 229
7-6 Problems involving geometric nonlinearity 238
7-7 Problems involving both material and geometric nonlinearity 242
References 242
Further reading 244

8 GENERALIZATION OF THE THEORY 245

8-1 Generalized terminology and concepts 245
8-2 The six-step finite element procedure in general terms 248
8-3 Fields of application 249
8-4 Mathematical bases of the finite element method 258
References 261
Further reading 264

PART C APPLICATIONS 265

9 STRUCTURAL MECHANICS 267

9-1 Summary of applications in structural mechanics 267
9-2 Finite element methods for structural mechanics 269
9-3 Special techniques 275
9-4 Example: Plane stress analysis of a gravity dam 281
9-5 Example: Axisymmetric stress analysis of a bolt-nut system 283
9-6 Example: Analysis of prestressed concrete reactor vessel 285
9-7 Example: Comparison of plate bending finite elements 287
9-8 Example: Analysis of an arch dam 291
9-9 Example: Axisymmetric shell applications 295
9-10 Example: Ship structures 300
9-11 Example: Analysis of folded plate by separation of variables 303
9-12 Example: Nonlinear analysis of thin plates 303
References 309
Further reading 312

10 SOIL AND ROCK MECHANICS 314

10-1 Summary of applications 314
10-2 Use of the finite element method in soil and rock mechanics 316
10-3 Example: Analysis of slopes in soils 329
10-4 Example: Bearing capacity and settlement analysis 331
10-5 Example: Static analysis of an earth dam 334
10-6 Example: Soil-structure interaction 336
10-7 Example: Slopes in jointed rocks 339

10-8 Example: Deep boreholes 340
10-9 Example: Tunnels 344
References 345
Further reading 350

11 DYNAMICS, INCLUDING EARTHQUAKE ANALYSIS 352

11-1 Summary of applications in dynamics 352
11-2 Formulation of inertial properties 353
11-3 Formulation of damping properties 358
11-4 Solution of transient problems by mode superposition 360
11-5 Example: Free vibration of thin plates 361
11-6 Example: Free vibration of cylindrical shells 363
11-7 Example: Response of earth dam by mode superposition 364
11-8 Example: Nonlinear dynamic analysis of underground structures 371
11-9 Example: Analysis of an earth dam failure 374
References 377
Further reading 379

12 TORSION, HEAT CONDUCTION, SEEPAGE 380

12-1 Use of the finite element method 380
12-2 Example of a formulation: Seepage 384
12-3 Numerical example: Steady confined seepage 387
12-4 Torsion of prismatic shafts 389
12-5 Example: Transient heat conduction 393
12-6 Example: Steady confined seepage under a sheet-pile wall 393
12-7 Example: Transient confined seepage in layered aquifers 397
12-8 Example: Steady unconfined seepage through an earth dam 397
12-9 Example: Transient unconfined seepage 399
References 403
Further reading 405

13 THERMOELASTICITY, CONSOLIDATION, HYDROELASTICITY 406

13-1 Example: Stress analysis for thermal and pore pressure effects 407
13-2 Example: Heating of linear thermoelastic half space 407
13-3 Example: Terzaghi's consolidation 411
13-4 Example: Motion of fluid in flexible container 412
References 414
Further reading 415

14 MISCELLANEOUS APPLICATIONS 416

14-1 Example: Viscous behavior of clay soils 417
14-2 Example: Creep in concrete dams 422
14-3 Example: Flow of ideal fluids 423
14-4 Example: Flow of viscous fluids 426
14-5 Example: Oscillations of harbors and lakes 428
References 432
Further reading 433

15 CONCLUSION—ADVANTAGES AND LIMITATIONS OF THE METHOD 435

15-1 Advantages 435
15-2 Limitations 437
15-3 Conclusions 438
Further reading 438

APPENDIX I ILLUSTRATIVE COMPUTER CODE 439

I-1 Introduction 439
I-2 Explanation of subroutines 440
I-3 Flow chart 441
I-4 Definition of variables 442
I-5 Guide for data input 444
I-6 Fortran listing 447
I-7 Sample input/output 458
I-8 Possible modifications 461
References 461
Further reading 462

APPENDIX II ABBREVIATIONS FOR REFERENCES 463

Author Index 465

Subject Index 469