CONTENTS

I.	INTRO	DUCTION	1
Ref	erences t	o Chapter I	3
II.	SUMM	ARY, CONCLUSIONS AND RECOMMENDATIONS	5
1.	Plasma	performance	5
	1.1.	Bulk heating	5
	1.2.	Current drive	7
	1.3.	Beta limits and energy confinement	8
	1.4.	Other issues	9
2.	Impuri	ty control and first wall	10
	2.1.	Poloidal divertor and pumped limiter	10
	2.2.	First-wall design	14
	2.3.	Erosion due to disruptions	14
	2.4.	Other impurity control methods	15
3.	Testing	ç	15
	3.1.	Fluence requirements for structural materials	
		radiation damage tests	15
	3.2.	Long-term operation component reliability	16
	3.3.	Blanket testing requirements	16
4.	Tritiun	n and blanket	16
	4.1.	Tritium permeation	16
	4.2.	Tritium contamination in reactor room	17
	4.3.	Tritium-breeding blanket	18
	4.4.	Tritium inventory	19
	4.5.	Safety considerations	19
5.	Mechar	nical configuration	20
	5.1.	Toroidal field (TF) coil size	20
	5.2.	Torus segmentation	20
	5.3.	Universal design concept	21
6.	Magnet	tics and torus electromagnetics	22
	6.1.	Magnetic systems	22
		6.1.1. Conductor/coolant options for TF coils	22
		6.1.2. Fault studies	23
		6.1.3. Toroidal field coil R and D requirements	23

		6.1.4. PF coil distribution studies	23	
		6.1.5. PF coil design	23	
		6.1.6. PF system fault studies	24	3
	6.2.	Torus electromagnetics	24	5
		6.2.1. Disruption effect	24	
		6.2.2. Passive stabilization	25	
		6.2.3. Active stabilization	25	2
		6.2.4. Start-up	26	2
7.	Cost-r	isk-benefit and schedule	26	5
	7.1.	Cost reductions	26	
	7.2.	Cost-risk-benefit assessment of performance objectives	27	-
	7.3.	Schedule	28	3
8.	Resea	rch and development	29	3
9.	Concl	usion	29	3
10.	Recor	nmendation for future work	29	
III.	INTO	R CONCEPT	33	3
1	Dala	of INTOD in the fusion programme	22	
1. ว	INITO	P abiactivas	33 25	1 N
2. 2	Design	A description	33 20	4. M 5 C
5.	2 1	Overviewe	30	J. S Doford
	5.1. 2 2	Diversion having	20 42	Refere
	5.2. 2.2	Mashaniaal configuration and maintaneous	45	
	3.3.	2.2.1 Toroidal magnetic field soil design according	40	IV. P
		5.5.1. Toroidal magnetic field coll design – access	47	
		requirements	47	1. P
		3.3.2. Poloidal magnetic field coil system	48	1
		3.3.3. Combined cryogenic and torus vacuum chamber		
		topology	49	
		3.3.4. Torus modularization and segmentation	49	
		3.3.5. Impurity control	49	1
		3.3.6. Structural support system	55	1
		3.3.7. Tokamak radial build	55	2. N
		3.3.8. Dedicated torus sectors	55	2
		3.3.9. Assembly and maintenance	55	
	3.4.	Magnetic and electrical systems	57	
		3.4.1. Toroidal field coil system	57	
		3.4.2. Poloidal field coil system	57	
		3.4.3. Active position control and start-up voltage	59	2
		3.4.4. Alternating current power system	60	з. т
		3.4.5. TF coil power conversion and protection	61	
		3.4.6. PF coil power conversion and protection	61	Ū
		3.4.7. Electrical energy storage system	62	

		3.4.8. Torus electromagnetics	63
		3.4.9. Cryostat	63
		3.4.10. Cryogenic system	63
	3.5.	Heating and fuelling systems	64
		3.5.1. Ion cyclotron heating system	64
		3.5.2. Electron cyclotron start-up assist system	66
		3.5.3. Fuelling system	68
	3.6.	First-wall system	68
	3.7.	Impurity control system	72
		3.7.1. Divertor option	72
		3.7.2. Limiter option	74
	3.8.	Tritium-breeding blanket	75
	3.9.	Radiation shield system	81
	3.10.	Tritium and vacuum systems	83
		3.10.1. Tritium systems	83
		3.10.2. Torus vacuum system	84
	3.11.	Site criteria and facility layout	85
		3.11.1. Site criteria	85
		3.11.2. Facility layout	86
4.	Machir	ne operation and test programme	86
5.	Schedu	ıle	91
Refe	erences	to Chapter III	93

IV. PLASMA CONFINEMENT AND CONTROL

1.	Plasma	confinement and beta limits	95
	1.1.	Experimental status	96
		1.1.1. Pre-saturation auxiliary-heating regime	96
		1.1.2. Saturated auxiliary-heating regime	100
		1.1.3. Particle transport	101
	1.2.	Ideal-MHD limits	102
	1.3.	Discussion and conclusions	104
2.	Modell	ling of plasma energetics	105
	2.1.	Ripple losses	105
		2.1.1. Thermal ripple losses	105
		2.1.2. Suprathermal ripple losses (beam ions and	
		fusion α -particles)	110
		2.1.3. Conclusions	112
	2.2.	Neutral-beam heating energy and power	113
3.	Discha	rge control issues	115
	3.1.	Burn temperature control and shut-down	115
		3.1.1. Burn control by a variable toroidal ripple	116

3.1.2. Burn control at a	beta limit	117
3.1.3. Burn control by i	mpurity injection	117
3.1.4. Burn control by r	nodulation of fuelling	117
3.1.5. The compression-	decompression scheme	118
3.1.6. Control by auxilia	ry heating	118
3.1.7. Shut-down	-	118
3.1.8. Conclusions		119
3.2. Equilibrium control requi	rements	119
3.3. Disruption characteristics	and control	121
4. Conclusions for INTOR		123
References to Chapter IV		126

V. RADIO-FREQUENCY HEATING AND CURRENT DRIVE

4.

1.	Physics	s basis		127
	1.1.	Ion cy	clotron heating to ignition	127
		1.1.1.	Experimental status	129
		1.1.2.	Comparison between ICRF theory and experiment	132
		1.1.3.	Code development for INTOR applications	134
		1.1.4.	Conclusions and choice of heating mode for	
			INTOR	135
	1.2.	Lower	hybrid heating to ignition	137
		1.2.1.	Experimental data base and physics mechanisms	137
		1.2.2.	Modelling of lower-hybrid heating and parameter	
			choice of a heating system for INTOR	141
		1.2.3.	Conclusions	143
	1.3.	Start-u	p assist	143
		1.3.1.	Experimental data base for radio-frequency	
			start-up assist	144
		1.3.2.	Modelling of start-up assist by electron	
			cyclotron waves	146
		1.3.3.	Profile control by electron cyclotron waves	147
		1.3.4.	Conclusions	150
	1.4.	Curren	t drive	151
		1.4.1.	Survey of current drive techniques	151
		1.4.2.	Status of lower hybrid current drive experiments	153
		1.4.3.	Prospects for tokamak reactors	155
2.	Launch	ing syst	tems	157
	2.1.	Ion cyc	clotron wave launching system	157
		2.1.1.	Design concepts	157
		2.1.2.	Conclusions	166

	2.2.	Lower hybrid launching system	166
		2.2.1. Design concepts	167
		2.2.2. Conclusions	173
	2.3.	Electron cyclotron wave launching system	175
		2.3.1. Design concept	175
		2.3.2. Conclusions	178
3.	Conclu	usions and reference heating systems for INTOR	179
	3.1.	Heating	179
	3.2.	Current drive	181
	3.3.	Recommendations	182
Refe	erences	to Chapter V	183
VI.	IMPUI	RITY CONTROL PHYSICS	185
			105
1.	Introd	uction	185
2.	Pumpe	ed limiter	187
	2.1.	Introduction	187

4.	rumpt		107
	2.1.	Introduction	187
	2.2.	Location	189
	2.3.	Low edge density – high edge temperature	
		(with low radiation)	191
	2.4.	High edge density – medium edge temperature	
		(with low radiation)	193
	2.5.	High edge density – low edge temperature	
		(with high radiation)	195
3.	Single-	null poloidal divertor	200
	3.1.	Introduction	200
	3.2.	Low-density (pellet-fuelled) plasma	202
	3.3.	High edge density – medium or low edge temperature	203
4.	Pumpi	ng and neutral-particle dynamics	206
	4.1.	Introduction	206
	4.2.	Limiter pumping	208
	4.3.	Divertor pumping	209
	4.4.	Neutral-particle dynamics	209
5.	Other	studies	211
	5.1.	Local hybrid divertor	211
	5.2.	Charge state distribution of impurity ions in the	•
		boundary plasma	214
	5.3.	Effects of inclinations of magnetic field upon sputtering	
		and secondary-electron emission	216
	5.4.	Impurity screening	218
	5.5.	Beam trapping in radiating plasma edge	219
	5.6.	Neutral-beam-driven impurity flow reversal	219

6	Conc	lusion	220		116 Redenosited material
0.	6.1	Boundary plasma conditions	220		4.1.0. Re-deposited material
	6.2	Single-null poloidal divertor	220		4.2.1 Bulk properties
	63	Pumped limiter	222		4.2.2 Radiation affacts
	0.5.	6.3.1 Condition: high edge density modium	222		4.2.2.1 Conner
		edge temperature (low radiation with			4.2.2.1. Copper
		low or medium sheath temperature)	222		4.2.2.2. Valiaulum $4.2.2.3$. Zirconium
		6.3.2 Condition: high edge density medium	222		423 Corrosion/compatibility
		edge temperature (high radiation with			4.2.4 Exprision
		very low sheath temperature)	222	5	Tile attachment concents and fabrication
	64	Comparison of divertor and limiter	223	5.	5.1 Tile attachment concepts and fabrication
	6.5	Recommendations based upon physics issues	223		5.1. The attachment concepts
R	eferences	to Chapter VI	224		5.1.2 Radiation-robus conduction-coole
10			224		5.1.3 Conduction-cooled concept
v	T IMPL	DITY CONTROL AND EIDET WALL ENGINEEDING	225		5.2 Fabrication
•1	u. mu u	ATT I CONTROL AND FIRST-WALL ENGINEERING	225		5.2.1 Granhite
1.	Intro	duction	225		5.2.2. Silicon carbide
2.	Opera	ting conditions	226		5.2.3 Bervllium
	2.1.	Common parameters	226		5.2.4. Beryllium oxide
	2.2.	Divertor/first wall	229		5.2.5. Tungsten
		2.2.1. Low temperature at divertor plate	229		5.2.6. Tantalum
		2.2.2. Medium temperature at divertor plate	229	6	Thermal hydraulic and stress analysis
	2.3.	Limiter/first wall	229	0.	6.1 Limiter design description
		2.3.1. Low edge temperature	229		6.2 Limiter temperature distribution
		2.3.2. Medium edge temperature	230		6.3. Stress analysis
		2.3.3. High edge temperature	230		6.4. Conclusions
3.	Mecha	anical configuration	232	7.	Electromagnetics
	3.1.	Divertor	232		7.1. Introduction
	3.2.	Pumped limiter	232		7.2. Analysis without conducting-shell effect
		3.2.1. Location	233		7.3. Analysis with conducting first wall
		3.2.2. Limiter shape	234		7.3.1. Variation of force with first-wall
		3.2.2.1. The plate limiter	235		7.3.2. Variation of force with limiter re
		3.2.2.2. The tube limiter	238		7.4. Induced voltages between limiter segmen
	3.3.	First wall	239	8.	Disruptions
4.	Mater	ials considerations	239		8.1. Disruption scenario
	4.1.	Plasma-side materials	239		8.2. Thermal response
		4.1.1. Physical sputtering	239		8.3. Melt layer stability
		4.1.2. Chemical sputtering	243	9.	Erosion/re-deposition
		4.1.3. Arcing	246		9.1. Introduction
		4.1.4. H/He retention/release	248		9.2. Computational models
		4.1.5. Bulk properties and radiation effects	249		9.3. Limiter analysis
		4.1.5.1. Low-Z materials	249		9.4. Divertor
		4.1.5.2. High-Z materials	251		

		4.1.6. Re-deposited material	252
	4.2.	Heat sink materials	254
		4.2.1. Bulk properties	254
		4.2.2. Radiation effects	255
		4.2.2.1. Copper	255
		4.2.2.2. Vanadium	257
		4.2.2.3. Zirconium	257
		4.2.3. Corrosion/compatibility	257
		4.2.4. Fabrication	258
5.	Tile at	tachment concepts and fabrication	258
	5.1.	Tile attachment concepts	258
		5.1.1. Radiation-cooled concept	260
		5.1.2. Radiation-plus-conduction-cooled concept	260
		5.1.3. Conduction-cooled concept	261
	5.2.	Fabrication	261
		5.2.1. Graphite	261
		5.2.2. Silicon carbide	262
		5.2.3. Beryllium	263
		5.2.4. Beryllium oxide	263
		5.2.5. Tungsten	263
		5.2.6. Tantalum	264
6.	Therm	al hydraulic and stress analysis	264
	6.1.	Limiter design description	265
	6.2.	Limiter temperature distribution	267
	6.3.	Stress analysis	268
	6.4.	Conclusions	271
7.	Electr	omagnetics	27
	7.1.	Introduction	27
	7.2.	Analysis without conducting-shell effect	272
	7.3.	Analysis with conducting first wall	274
		7.3.1. Variation of force with first-wall time constant	276
		7.3.2. Variation of force with limiter resistivity	277
	7.4.	Induced voltages between limiter segments	277
8.	Disrup	otions	279
	8.1.	Disruption scenario	279
	8.2.	Thermal response	280
	8.3.	Melt layer stability	284
9.	Erosio	on/re-deposition	289
	9.1.	Introduction	289
	9.2.	Computational models	289
	9.3.	Limiter analysis	29
	0.4	Divertor	200

10.	Lifetin	ne analysis	302	3	Tritium
	10.1.	Maximum allowable thickness	303	•••	3.1.
		10.1.1. Maximum allowable temperature	303		3.2.
		10.1.2. Allowable thickness	305		3.3.
		10.1.3. Other limiting factors	306		3.4.
	10.2.	Lifetime estimates	307	4.	Tritium
		10.2.1. The limiter top surface	307		4.1.
		10.2.2. The leading edge	309		
		10.2.3. The first wall	309		
		10.2.4. First-wall strips	311		
	10.3.	Conclusions	312		
11.	Recon	mendations on design concepts	312		
	11.1.	Introduction	312		
	11.2.	Divertor	313		
		11.2.1. Low-edge-temperature regime	314		42
		11.2.2. Medium-edge-temperature regime	315		1.2.
	11.3.	Limiter	317		
		11.3.1. Low-edge-temperature regime	317		
		11.3.2. Medium-edge-temperature regime	318		
12.	Conclu	isions and recommendations	318		
13.	Maior	uncertainties and future effort	322		
	13.1.	Major uncertainties	322		
	13.2.	Future effort	323		
Ref	erences	to Chapter VII	324		
				5	Tritium
				5.	1 muum 5 1
VII	I. TRI	TIUM AND BLANKET	327		5.1.
1	T		227		5.2.
1.	Introa	uction	327		5.5. 5 1
2.		Tritical and the second s	328		5.4.
	2.1.	I ritium permeation rate	328		5.5.
		2.1.1. Theoretical models and calculations	329		5.6.
		2.1.2. Experimental results	331		5.7.
		2.1.3. Calculational results	333	6.	Safety
		2.1.4. First-wall permeation barriers	339		6.1.
		2.1.5. Gas release during dwell time and maintenance	342		6.2.
		2.1.6. Radiation effects	343	Ref	erences to
		2.1.7. Conclusions	346		
	2.2.	Tritium processing of the primary coolant	347	IX.	MAGNI
		2.2.1. Methods for tritium separation from water	347	1	TT
		2.2.2. Cost and process comparison	348	1.	1 F CO1
		2.2.3. Tritium concentration in water coolant	351		1.1.
	2.3.	Conclusions and recommendations	352		
	2.3.	Conclusions and recommendations	352		

02	3.	Tritium contamination of reactor environment	353
)3		3.1. Sources of tritium contamination	353
)3		3.2. Tritium concentration levels in air	355
)5		3.3. Air detritiation system and cost	357
)6		3.4. Personnel access	360
)7	4.	Tritium-breeding blanket	362
)7		4.1. Solid breeder materials	362
)9		4.1.1. New data on solid breeder materials properties	362
)9		4.1.2. Radiation effects	370
1		4.1.3. Tritium recovery	370
2		4.1.4. Blanket design	375
2		4.1.5. Methods of accommodating power variations	
2		in the blanket	376
3		4.1.6. Hydrogen influence on weldability	378
4		4.2 Liquid breeders	379
15		4.2.1 Data hase	379
17		4.2.1.1 Physical and chemical properties	379
17		4.2.1.2 Compatibility with structural materials	379
18		4 2 1 3 Chemical reactivity	383
8		4.2.2 Design aspects	384
22		4.2.2. Design aspects	501
22		into coolant	387
23		4222 Pre-heating systems	388
24		4.2.2.2. The heating systems	380
	5	Tritium system	380
	5.	5.1 Introduction	389
27		5.1. Introduction	300
17		5.2. Trasma reprocessing system	301
27		5.5. Directing trittenin processing system	302
10		5.5 Tritium inventory	303
20		5.6 Atmosphere processing system	304
29		5.7 Conclusions	304
22	6	Safaty considerations	396
))))	0.	6.1 Accident analysis	396
12		6.2 INTOP rediction impact on population	308
+2	Def	0.2. IN TOK radiation impact on population	<i>39</i> 8 <i>4</i> 0 <i>4</i>
+3	Reli	erences to Chapter vill	404
+0	IV	MACNETS	407
+/	IX.	MAGNEIS	407
+/	1.	TF coil system	407
+ð - 1		1.1. TF coil design and concept evaluation	408
51		1.1.1. Alternative coolant/conductor designs	409
02		1.1.1.1. Design descriptions	409

			1112 Heat treatment of superconductors	419
			1.1.1.3. Stabilization analysis	421
		1.1.2	Toroidal field coil structure definition	421
		1.1.3	Comparison of alternative approaches	425
			1.1.3.1. Maturity of technology	425
			1.1.3.2. Reactor compatibility	426
			1.1.3.3. Reliability	427
			1.1.3.4. Complexity	427
			1.1.3.5. Summary of comparative study	427
	1.2.	Power	conversion and protection	428
	1.3.	Safety	aspects and fault conditions	431
		1.3.1.	Abnormal operating conditions	431
		1.3.2.	Accident situations	433
		1.3.3.	TF coil sensitivity to short-circuit fault	433
		1.3.4.	Time required for replacement of one TF coil	436
	14	Researc	ch and development required	436
		1.4.1	Intermediate-scale coil fabrication and operation	438
		1.4.2	TF coil superconductor property cost	
			and improvement	438
		1.4.3	TF coil mechanical and electrical properties	
			of composites and components	439
		1.4.4	Magnet status detection techniques	439
		1.4.5.	Low-eddy-current-loss vessel for He II	440
	1.5.	Conclu	sions	440
2.	PF coil	system		441
	2.1.	Introdu	uction	441
	2.2.	PF dist	ribution studies	441
	2.3.	Typica	1 PF coil distributions	448
	2.4.	PF coil	design (central solenoid coil/ring coil)	449
		2.4.1.	Conductor and cooling method	449
		2.4.2.	Coil structure and mechanical stress	449
		2.4.3.	AC losses in PF coils	455
		2.4.4.	Stability analysis	456
	2.5.	Power	handling and conversion	457
	2.6.	Safety	aspects and fault conditions	464
	2.7.	Resear	ch and development required	466
	2.8.	Conclu	isions	466
Refe	erences	to Chap	ter IX	468
Х.	ELECI	ROMA	GNETICS	469
1.	Influer	ice of el	ectromagnetics on machine design	469
2.	Plasma	disrupt	ion effects	470

	2.1. Heating of the coils	470
	2.2. Forces, torques and overturning moments	473
	2.3. Induced voltages	480
	2.3.1. Voltages between limiter segments	481
	2.3.2. PF coil currents and voltages	482
	2.3.3. Sector gap voltages	483
3.	Passive stabilization	487
	3.1. Vertical stabilization	487
	3.2. Radial stabilization	498
4.	Active stabilization and control	498
	4.1. Vertical control	501
	4.2. Radial control	504
5.	Other studies	507
	5.1. Field and flux penetration through shells	507
	5.2. Start-up	509
6.	Conclusions	512
	6.1. Disruption effects	512
	6.2. Passive stabilization	513
	6.2.1. Stabilization concept	513
	6.2.2. Passive elements	514
	6.3. Active position control	514
	6.4. Start-up	515
	6.5. Eddy current modelling codes	515
Ref	ferences to Chapter X	516
	•	
XI.	MECHANICAL CONFIGURATION	517
1.	Introduction	517
	1.1 Objectives	517
	1.2 Design requirements	519
	1.3 Design summary	519
2	TF system	521
2.	2.1 Evaluation of TE coil size	521
	2.1. Evaluation of 11 con size	521
	2.1.2 Winding configuration	524
	2.1.2. Structural design implications	524
	2.1.3. Suburtural design inipitations	524
	2.2. Design description	521
	2.5. Con maintenance and replacement approach	527
2	2.4. Supporting analysis	522
5.	2.1 Comparison of Dhase One and Dhase Two A acid sustains	522
	2.2 Dumped limiter versus poloidal diverter configuration	523
	5.2. rumped-minter versus poloidal-divertor configuration	333

	3.3.	Structural design, maintenance and access	535
	3.4.	Universal PF configuration	537
4.	Vacuu	m boundary	539
	4.1.	Design options	539
	4.2.	Evaluation and selection	547
		4.2.1. Approach to evaluation	547
		4.2.2. Evaluation procedure	547
		4.2.3. Choice of the reference option	549
	4.3.	Design description	549
	4.4.	Supporting analysis	553
5.	Torus	system	555
	5.1.	INTOR Phase One – torus concept	555
	5.2.	Segmentation options	559
	5.3.	Evaluation and selection	560
	5.4.	Design description	561
		5.4.1. 12-sector configuration option	561
		5.4.2. 24-sector configuration options	563
	5.5.	Supporting analysis	573
6.	Impuri	ity control	574
	6.1.	Pumped-limiter configuration	574
		6.1.1. Alternative concept (outboard single pumped	
		limiter)	575
	6.2.	Poloidal-divertor configuration	576
	6.3.	Universal concept	578
7.	Heatin	g system	578
	7.1.	Radio-frequency heating and start-assist systems	579
	7.2.	Neutral-beam heating systems	580
•	7.3.	Conclusions	580
8.	Conclu	isions and recommendations	581
Ref	erences	to Chapter XI	582
XII	FNGIN	JEERING TESTING	585
	LIVOI		000
1.	Introd	uction	585
2.	Structu	aral materials testing	587
	2.1.	Introduction	587
	2.2.	Evaluation methods	587
	2.3.	Data base and estimates of uncertainty	589
		2.3.1. Stainless-steel data	589
		2.3.2. Vanadium alloy data	595
	2.4.	Strategy for fusion materials development	596

2.4.1. Materials development 597

		2.4.2. Boundary conditions	599
		2.4.3. Development scenarios	600
		2.4.4. Choice of scenario	605
		2.4.5. Strategy	605
	2.5.	Conclusions	606
		2.5.1. Fluence criteria and risk for stainless steel	607
		2.5.2. Fluence criteria and risk for an advanced	
		allov (vanadium)	608
3.	Blanke	et testing	610
	3.1.	Introduction	610
	3.2.	Evaluation methods	611
		3.2.1. Selection of tests for evaluation	611
	3.3.	Results of the evaluation	614
		3.3.1. Neutronics test	614
		3.3.2. Tritium recovery tests	616
		3.3.3. Materials compatibility tests	617
		3.3.4. Heat recovery tests	618
	3.4.	Summary	619
4.	Benefi	ts to DEMO of long-term operation of	
	INTO	R components	620
	4.1.	Approach	620
	4.2.	Potential benefits of long-term INTOR component	
		operation	620
	4.3.	INTOR and DEMO requirements	621
	4.4.	Determination of test time required in INTOR	627
		4.4.1. Confidence building	627
		4.4.2. Reliability growth	628
	4.5.	Specific component evaluation	631
	4.6.	Future effort required	631
5.	Conclu	usions	632
6.	Appen	dix: Test modules for simultaneous tritium breeding	
	and ele	ectricity generation	634
	6.1.	Introduction	634
	6.2.	Overall design requirements	634
	6.3.	General considerations for blanket design	635
		6.3.1. Neutron multiplier	635
		6.3.2. Coolant	635
	6.4.	Helium-cooled solid-breeder blanket	636
	6.5.	Water-cooled solid-breeder blanket	637
	6.6.	Carbon-dioxide liquid-metal breeder blanket	642
	6.7.	Conclusions	643
Ref	erences	to Chapter XII	643

XII	I. COST AND SCHEDULE	645	
1.	Introduction		
2.	Cost evaluation	646	
	2.1. Assessment of benchmark options for cost estimation		
	and direct capital costs	646	
	2.2. Modification for availability and reliability	651	
	2.3. Indirect capital cost	654	
	2.4. Operation costs	655	
	2.5. Total cost and result evaluation	658	
3.	Major influential factors on cost	662	
	3.1. Key parameters for cost reduction	662	
	3.2. Key options for cost reduction	668	
4.	Schedule evaluation	669	
	4.1. Introduction	669	
	4.2. Effect of start date on project initiation	672	
	4.3. Effect of start date on degree of support obtained		
	from complementary R and D programme	672	
	4.4. Effect of start date on a demonstration point ('DEMO')	675	
5.	Conclusions	675	
Ref	erences to Chapter XIII	677	
XIV	/. COST-RISK-BENEFIT	679	
1.	Introduction	679	
2.	Cost-risk-benefit study		
		679	
	2.1. Risk-benefit assessment	679 682	
	2.1. Risk-benefit assessment 2.2. Cost comparison	679 682 685	
	 2.1. Risk-benefit assessment 2.2. Cost comparison 2.3. Cost-risk-benefit assessment performance objectives 	679 682 685 690	
	 Risk-benefit assessment Cost comparison Cost-risk-benefit assessment performance objectives 	679 682 685 690	
XV.	 2.1. Risk-benefit assessment 2.2. Cost comparison 2.3. Cost-risk-benefit assessment performance objectives RESEARCH AND DEVELOPMENT 	679 682 685 690 693	
XV .	 2.1. Risk-benefit assessment 2.2. Cost comparison 2.3. Cost-risk-benefit assessment performance objectives RESEARCH AND DEVELOPMENT Introduction 	679 682 685 690 693	
XV . 1. 2	 2.1. Risk-benefit assessment 2.2. Cost comparison 2.3. Cost-risk-benefit assessment performance objectives RESEARCH AND DEVELOPMENT Introduction Status of R and D identified in Phase One 	679 682 685 690 693 693	
XV . 1. 2. 3	 2.1. Risk-benefit assessment 2.2. Cost comparison 2.3. Cost-risk-benefit assessment performance objectives RESEARCH AND DEVELOPMENT Introduction Status of R and D identified in Phase One Research and development needs identified in Phase Two A 	679 682 685 690 693 693 693 695	
XV . 1. 2. 3.	 2.1. Risk-benefit assessment 2.2. Cost comparison 2.3. Cost-risk-benefit assessment performance objectives RESEARCH AND DEVELOPMENT Introduction Status of R and D identified in Phase One Research and development needs identified in Phase Two A 3.1. Physics 	 679 682 685 690 693 693 693 695 695 	
XV. 1. 2. 3.	 2.1. Risk-benefit assessment 2.2. Cost comparison 2.3. Cost-risk-benefit assessment performance objectives RESEARCH AND DEVELOPMENT Introduction	 679 682 685 690 693 693 693 695 695 695 	
XV. 1. 2. 3.	 2.1. Risk-benefit assessment 2.2. Cost comparison 2.3. Cost-risk-benefit assessment performance objectives RESEARCH AND DEVELOPMENT Introduction Status of R and D identified in Phase One Research and development needs identified in Phase Two A 3.1. Physics P.1. Plasma behaviour near beta limits P.2. Confinement scaling in auxiliary-heated discharges 	 679 682 685 690 693 693 693 695 695 696 	
XV . 1. 2. 3.	 2.1. Risk-benefit assessment 2.2. Cost comparison 2.3. Cost-risk-benefit assessment performance objectives RESEARCH AND DEVELOPMENT Introduction Status of R and D identified in Phase One Research and development needs identified in Phase Two A 3.1. Physics P.1. Plasma behaviour near beta limits P.2. Confinement scaling in auxiliary-heated discharges P.3. Plasma equilibrium control 	 679 682 685 690 693 693 693 695 695 695 696 697 	
XV. 1. 2. 3.	 2.1. Risk-benefit assessment 2.2. Cost comparison 2.3. Cost-risk-benefit assessment performance objectives RESEARCH AND DEVELOPMENT Introduction Status of R and D identified in Phase One Research and development needs identified in Phase Two A 3.1. Physics P.1. Plasma behaviour near beta limits P.2. Confinement scaling in auxiliary-heated discharges P.3. Plasma equilibrium control P.4. Plasma profile control 	 679 682 685 690 693 693 693 695 695 696 697 698 	
XV. 1. 2. 3.	 2.1. Risk-benefit assessment 2.2. Cost comparison 2.3. Cost-risk-benefit assessment performance objectives RESEARCH AND DEVELOPMENT Introduction Status of R and D identified in Phase One Research and development needs identified in Phase Two A 3.1. Physics P.1. Plasma behaviour near beta limits P.2. Confinement scaling in auxiliary-heated discharges P.3. Plasma equilibrium control P.4. Plasma profile control P.5. Reactor prototypical ICRF heating 	679 682 685 690 693 693 693 695 695 695 695 695 696 697 698 698	
XV. 1. 2. 3.	 2.1. Risk-benefit assessment 2.2. Cost comparison 2.3. Cost-risk-benefit assessment performance objectives RESEARCH AND DEVELOPMENT Introduction Status of R and D identified in Phase One Research and development needs identified in Phase Two A 3.1. Physics P.1. Plasma behaviour near beta limits P.2. Confinement scaling in auxiliary-heated discharges P.3. Plasma equilibrium control P.4. Plasma profile control P.5. Reactor prototypical ICRF heating P.6. ICRF code development 	679 682 685 690 693 693 693 695 695 695 696 697 698 698 698	

P.8. High-power LH and EC heating	700
P.9. Quasi-steady-state mode of operation	701
P.10. Characterization of high- and low-temperature	
edge regimes	702
P.11. Edge particle and energy fluxes	703
P.12. Divertor channel behaviour	703
P.13. Impurity behaviour	704
P.14. Limiter pumping characteristics	705
P.15. Molecular and low-temperature charge-exchange data	706
3.2. Nuclear	706
N.1. Self-sputtering yield of main candidate materials	706
N.2. Sputtering by tritium	707
N.3. Properties of re-deposited metals	708
N.4. Irradiation effects on non-replaceable high-flux	
materials (60 dpa)	708
N.5. Irradiation effects on replaceable high-flux	
materials (30 dpa)	709
N.6. Tritium permeation and inventory, including	
irradiation effects	710
N.7. Eutectics development	711
N.8. 14-MeV neutronics integral experiments	712
3.3. Engineering	713
E.1. High-power ICRF system demonstration	713
E.2. Improved structural concepts for first wall/	
divertor/limiter	713
E.3. First-wall outgassing procedure	715
E.4. Tritium pellet injector	715
E.5. Superconductors for fields above 10T	716
E.6. Low-loss, high-current 8T superconductors	717
E.7. TF coil mechanical and electrical properties	717
E.8. Safety circuits to cope with short-circuiting	
of superconducting coils	718
E.9. Low-loss PF coil concept	718
E.10. Intermediate-scale PF coil demonstration	719
E.11. Computational tools for transient electromagnetics	719
E.12. Torus maintenance methods and procedures	720
E.13. Adequate torus resistance	720
E.14. Voltage withstand criteria for components	
within the torus	721
E.15. Pump development	721
E.16. PF coil power supply system optimization	722
References to Chapter XV	722

XV	I. DESIGN SPECIFICATIONS	723
XV	II. ADMINISTRATIVE APPENDICES	747
1.	INTOR Phase-Two-A Workshop Sessions	747
2.	European INTOR home-base organization	747
	2.1. Euratom INTOR Workshop Team	747
	Workshop participants and attendees	747
	INTOR/NET Steering Group	747
	Contributors to individual chapters	748
	Organizational index	754
3.	Japan INTOR Workshop Teams	755
	Workshop participants and attendees	755
	Contributors to individual chapters	755
	Organizational index	759
4.	USA INTOR Workshop Teams	760
	Workshop participants and attendees	760
	INTOR Review Committee	760
	Contributors to individual chapters	760
	Organizational index	765
5.	USSR INTOR Workshop Team	766
	Workshop participants and attendees	766
	Contributors to individual chapters	766
	Organizational index	772